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SYSTEM ANALYSIS

FOR THE

HUNTSVILLE OPERATIONAL SUPPORT CENTER

DISTRIBUTED COMPUTER SYSTEM

ANNUAL REPORT
MSSU-EIRS-EE-83-6
May 1982 - June 1983

Submitted by:

F. M. Ingels, Principal Investigator

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Electrical Engineering Department
Mississippi State, MS 39762
(601) 325-3912

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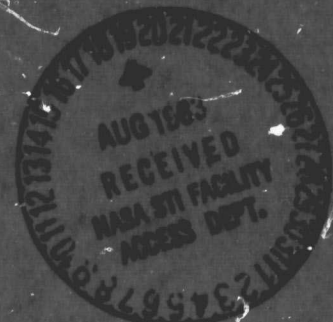Mississippi State University
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SYSTEM ANALYSIS

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DISTRIBUTED COMPUTER SYSTEMS

SUMMARY

The Huntsville Operations Support Center (HOSC) is a distributed computer system used to provide real time data acquisition, analysis and display during NASA space missions and to perform simulation and study activities during non-mission times. The primary purpose of this research is to provide a HOSC system simulation model that may be used to investigate the effects of various HOSC system configurations. Such a model would be valuable in planning the future growth of HC and in ascertaining the effects of data rate variations, update table broadcasting and smart display terminal data requirements on the HOSC HYPER channel network system.

A simulation model was developed and programmed in three languages BASIC, PASCAL, and SLAM. Two of the programs are included in this report, the BASIC and the PASCAL language programs. SLAM is not supported by NASA/MSFC facilities and hence was not included. The statistical comparison of simulations of the same HOSC system configurations are in good agreement and are in agreement with the operational statistics of HOSC that were obtained.

Three variations of the most recent HOSC configuration have been run and some conclusions drawn as to the system performance

under these variations. Section 3.4 discusses these results and conclusions.

LIST OF TABLES

LIST OF FIGURES

TABLE OF CONTENTS

TABLE OF CONTENTS (Continued)

1.0   INTRODUCTION

1.1   HOSC System Overview

Marshall Space Flight Center (MSFC), Huntsville, Alabama, has implemented the Huntsville Operations Support Center (HOSC) to provide real time data acquisition, analysis, and display during NASA space missions. The HOSC is a distributed computer system composed of a network of large minicomputers and various peripheral equipment. Primarily designed to provide support for the Space Shuttle, Space Telescope, and Space Laboratory missions, the HOSC has the inherent flexibility to be expanded to meet the needs of future missions as well as providing MSFC with a large computer resource that can be used to support several non-mission activities.

The HOSC facility has been structured to include five large minicomputers and various peripheral equipment. The current network computers are each semi-dedicated to specific mission tasks (e.g. Space Shuttle Main Engine Data Analysis) and include three Perkin Elmer 3244 computers, a Perkin Elmer 8/32c computer, two DEC VAX 11/780 computers and a DEC 11/24 computer. An important role of the Perkin Elmer computers is acting as real time data receivers for mission data arriving via satellite and direct ground links from the Kennedy Space Center Firing Room at Cape Canaveral FL. These computers also act as a gateway to the network for the data which is needed by other mission activities supported by the other computers and peripherals. Peripheral equipment in the system includes two twelve channel Genisco Digital Television (D/TV's), strip recorders, and numerous unintelligent data terminals.

Foreseeable future expansion will include at least five more mini-
computers, many more D/TV displays (possibly to 50), several more
strip recorders, and intelligent data terminals.

The HOSC currently provides support for MSFC non-mission
activities such as the Total POCC Preplanning Activity with future
expansion providing data management resources for other non-mission
activities. These activities might include the DEC IGDS (interactive
graphics) and XEROX SIGMA (text processing) operations. All of these
activities would be permitted use of the network resources through
the Network Systems Corporation HYPER channel broadband local area
network.

1.2   Scope of Report

In order to achieve the flexibility and efficiency needed by
the HOSC, an analysis of the present system has been performed. This
analysis coupled with projected system growth will insure that the
HOSC remains a viable computing resource for MSFC. This report
contains a summary of the baseline data gathered to begin the
analysis of the HOSC computer network, Section 2.0, results of the
analysis, Section 3.0, and a literature/bibliography Section 4.0.
The report describes in detail some of the network components and also
makes first iteration recommendations concerning network operations.
This document should not be considered an end item since work still
remains to be done in completely characterizing all the subtleties
of the HOSC system.

1.3 Conclusion

From the work done thus far in the program, several conclusions and recommendations can be made.

A. Proposed IGDS/SIGMA Interface With HOSC

Network Systems Corporation does not currently produce hardware for the HYPER channel to XEROX processor interface. Consequently, a great amount of effort would be required to interface the SIGMA system directly with the HOSC HYPER channel.[1] A possible solution might be to interface the XEROX SIGMA to the network through a HYPER channel supported processor such as another DEC VAX. Feasibility of the VAX/XEROX interface has not been explored and may also present problems. A definite possibility to solve this problem is to develop a suitable software/hardware approach.

The DEC IGDS system interfaces with the HYPER channel and will present no obvious problems since the PDP-11 processor interface adapters are currently marketed by Network Systems Corporation.

B. CSO/HOSC Link Via HOSC HYPER Channel Adapter 4 For OI Data Exchange

The current plan is to interface CSO with HOSC using a separate trunk of adapter 4. By connecting the two installations with a separate trunk, CSO will be disallowed easy and immediate access to the HOSC resources on the HYPER channel. Because of the HYPER channel adapter design, direct trunk to trunk exchange of data is not possible. For trunk to trunk transfers, data from the initiating trunk must be channeled

through a processor on the common adapter and retransmitted by the processor over the other trunk.[2] If however, it is desireable to prevent CSO from easy access to the total HOSC resources, then the use of separate trunk is a good approach.

C. Summary of Analysis Activity

Progress on the analysis of HOSC has so far been steady but somewhat slow due to the difficulty in obtaining some needed baseline data. Below is a summary of the documentation accumulated to conduct the analysis effort.

. Perkin Elmer Corporation

3240 User's Mannual 29-685

3240 Memory System Manual 29-688

8/32 User's Manual 29-394

8/32 Memory System Manual 29-428

(These manuals must contain the actual HOSC Computer internal DMA to I/O setup.)

. Network Systems Corporation

PI40 Peripheral Interface Manual

(Perkin Elmer I/O Bus Interface)

PI10 PI Manual or PI11 PI Manual

(Dependent on configuration of PDP-11 IGDS system: PI10 for DR11-B general purpose direct memory access or PI11 for DR70 MASSBUS interface.)

NETEX Software Documentation

. Marshall Space Flight Center

Completed system computer data rate flows.

D. Effects of Data File Dumps

It is desired to make large data file transfers on a periodic basis to refresh the data display terminals data base. This type of activity can create a log/jam effect on the most active data sources if the number of data bytes to be transferred are large enough to create waiting times. The basic relationship involves a tradeoff between the amount of storage of data by the data sources, their rate of data accumulation and the time requir.. to transfer the data files.

This problem is discussed in Section 3.3 and 3.4 in detail.

2.0   HOSC SYSTEM DETAILS

The primary purpose of the Huntsville Operation Support Center is providing MSFC engineers with a near real time summary of vital information describing the operational status of certain components of the Space Shuttle during pre-launch and launch activities. This information allows MSFC engineers and contractor personnel to act in a support capacity to mission personnel at Kennedy Space Center (KSC), Cape Canaveral, Florida, and also Johnson Space Center (JSC), Houston, TX. MSFC support is provided by teams responsible for the Space Shuttle Main Engine (SSME), External Tanks (ET), Solid Rocket Boosters (SRB), Main Propulsion System (MPS) and the Range Safety System (RSS). Additional mission support is provided for various mission activities and programs that are the responsibility of MSFC personnel.

> During powered flight, the HOSC will receive only data which is in the LPS (Launch Processing System) at KSC. The Shuttle support team will be in the HOSC during this phase of the mission and will be the point of contact with the JSC Mission Evaluation Room (MER) for problem discussion and resolution as required and will be on call during orbital operations. The Space Lab and experiment support team will be located in the HOSC during orbital operations when applicable
>
> Following completion of the active Shuttle vehicle support activities, data is recalled as required for more detailed analysis, and initial preparation is made to provide support to postflight evaluation.[3]

The HOSC is located in the west end of A-wing, building 4663 on Martin, Road, MSFC. Figures 1 and 2 show the functional components of the HOSC system and gives each component a referencing number that will be used in describing the system activities.

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Figure 1. Original HOSC HYPER Channel Network Configuration

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Figure 2. Proposed HYPER Channel Network Configuration

Figure 2a. Proposed HYPE Channel Network Configuration, Rev 1.
(MIPS Primary VAX 4 Connected to Adapter 2.)

2.1 HOSC System Activities

In addition to the mission activities, the HOSC also provides support to several non-mission activities at MSFC. Details of all the HOSC activities are described below and summarized in Table 1.

2.1.1 Total POCC Preplanning

The POCC activity is an ongoing simulation activity for which the HOSC lends computer resources. This activity is in no way keyed to the real time mission activities and must be viewed as a con tinuous daily activity.

The POCC activity's impact on the HYPER channel network is basically that of continuous data transfers between the MIPS Primary Computer (VAX4, A400 Adapter 2) and the MIPS Backup Computer (VAX1, A400 Adapter 5). During each 24 hour period 150,000 512-byte blocks of data are transferred. Six times each day, an 8344 byte block is transferred (50,000 bytes cummulative). The remaining 100,000 512-byte blocks are transmitted randomly, but on an evenly distributed basis, throughout the day.

2.1.2 ECIO Data Stream

The POCC activity generates a continual 51.2 kilobit/second data stream known as the Experimental Computer Input/Output (ECIO) data stream. This data stream is ongoing and concurrent with the POCC activity. Data is transferred from MIPS Backup (VAX1, A400 Adapter 5) to the Spacelab 8/32 (PE 8/32c, A400 Adapter 1).

TABLE 1. HOSC DATA TRANSFERS

I. ROUTINE DAILY ACTIVITIES (Launch Independent)

A. Total POCC Preplanning Activity

Resources involved: MIPS Primary (VAX4, Adapter 2)
                     MIPS Backup (VAX1, Adapter 5)

Quantity of data: 150,000 512-byte blocks daily

B. ECIO Data Stream (Generated by POCC)

Resources involved: MIPS Backup (VAX1, Adapter 5)
                     Spacelab 8/32 (PE 8/32c, Adapter 1)

Quantity of data: 51.2 K bits/second concurrent with POCC.

C. IGDS/SIGMA Activity (Proposed)

Resources Involved: DEC IGDS and XEROX SIGMA and
                     communication with other resources
                     as needed.

Quantity of data: TBD

II. LAUNCH DAY ACTIVITIES:

A. Routine Daily Activities (See Above)

B. Main Engine Data

Resources Involved: STS Primary (PE 3244, Adapter 1)
                     MIPS Backup (VAX1, Adapter 5)

Quantity of Data: 50 K bit/second stream (T-8 hours to T+12 minutes)

C. OI Data Stream

Resources Involved: FEB SSME (PE 3244, Adapter 4)
                     CSO Computers (Adapter 4)
                     STS Primary (PE 3244, Adapter 1)
                     MIPS Backup (VAX1, Adapter 5)

Quantity of Data: 128 K bit/second (T-9 sec to T+12 minutes)
                   into FEP and then to CSO. 40% will also
                   be transferred to STS and MIPS.

TABLE 1.   HOSC DATA TRANSFERS (Continued)

D.   Engineering Display Changes

Resources Involved: STS Primary (PE 3244, Adapter 1)
                      STS Backup (PE 8/32 Adapter 1)
                      Spacelab 8/32 (PE 8/32, Adapter 1)

Quantity of Data: Insignificant

2.1.3 Main Engine Data

Space Shuttle Main Engine data is collected and dissiminated
at the HOSC during a launch day activity only. Data is funneled
through the HYPER channel network to MIPS Backup (VAX1, A400
Adapter 5) via STS Primary (PE 3244, A400 Adapter 1). STS Primary
accepts a continual 50 kilobit per second data stream directly from
the KSC firing room from 9 seconds before launch to 12 minutes after
launch (MECO). Approximately 24 percent of this 50 Kb/s stream
(12 Kb/s) is transferred over the network to MIPS Backup.

2.1.4 OI Data Stream

The OI data stream is a 128 kilobit per second data stream
arriving at FEP SSME (PE 3244, A400 Adapter 4) on launch day only
(t-9 seconds to T+12 minutes). This data will have a much greater
future impact on the network than it does currently. The SSME computer
acts as a front end processor for accepting this data stream from
Goddard Space Flight Center and then writes the received data directly
onto a magnetic tape for later transport to CSO. Later in the program
this data will be shipped in its entirety over a separate HYPER channel
trunk attached to A400 Adapter 4 to CSO. Additionally, about 40 per-
cent of the data stream will be shipped over the HOSC network to supply
and supplant the data currently being transferred by the Main Engine
Data Activity.

2.1.5 Engineering Display Changes

This activity adds almost insignificantly to the total HYPER
channel trunk traffic. The activity involves a transfer from STS
Primary to STS Backup and the Spacelab 8/32 (PE3244 to two PE8/32's,

A400 Adapter, 1 only) of the name of each engineering console
display format that is changed during the pre-launch and launch
activities (T-9 seconds to T+12 minutes). This activity will be
ignored in the HOSC system analysis due to its negligible contribution
to total HYPER channel system traffic.

2.1.6 Proposed Activities

The most immediate proposed expansion of the HOSC network would
allow two other non-mission activities access to the resources of
the HOSC network. This activity would specify an additional A400
Adapter to allow resource sharing with the XEROX SIGMA system and
the DEC PDP-11 IDGS system. Direct interface with the A400 is
available for the PDP-11 but not for the XEROX system. A possible
solution to allow the XEROX system access to the network through the
A400 might be to use a compatible computer such as a DEC VAX 11/780
as a front end processor for the XEROX system. This activity is
incompletely specified and will not affect the immediate analysis
of the HOSC system.

2.2 HOSC System Components

The heart of the HOSC system is the Network Systems Corporation
HYPER channel. The HYPER channel is a high speed digital communica-
tions facility that is used for interconnection of computer resources
in a computing installation. The following sections describe the
computer resources of the HOSC and how they are interconnected using
the HYPER channel.

2.2.1 Computer Resources

2.2.1.1 DEC VAX 11/780

The HOSC makes use of Digital Equipment Corporation's VAX 11/780 computer as computational devices. The system currently includes two VAX computers (VAX1 and VAX4) designated as MIPS Primary and MIPS Backup. Future expansion will add two other VAX computers (VAX2 and VAX3) designated as Software Development and Space Telescope.

VAX computers support a 32-bit work architecture that is designed to aid in system throughput. Data transfers are accomplished via a 32-bit high speed data structure. This structure ties together the central processor, main memory, the UNIBUS subsystem, the MASS BUS subsystem and the DR780 high speed direct memory access subsystem. The 32-bit word architecture of the VAX establishes a virtual address space of 4.3 billion bytes of user addressable memory. A conceptual diagram of the VAX 11/780 bus structure is shown in Figures 3 and 4.

The Synchronous Backplane Interface (SBI) is the data path that links the central processor, the memory subsystem and the hardware adapters provided for the UNIBUS and MASSBUS. When interfaced to the SBI, the memory subsystem, the central processor, and the I/O controllers are known as NEXUSs.

All NEXUSs receive every SBI transfer. Logic in each NEXUS determines whether the NEXUS is the designated receiver for this transfer. Data transfers can occur from

> CPU to memory subsystem
>
> I/O controller to memory subsystem
>
> CPU to I/O controllers.

Figure 3. Block Diagram of VAX 11/780 Computer

17

Figure 4. Basic Bus Configuration of VAX 11/780

The maximum, aggregate data transfer rate on the SBI is 13.3 megabytes per seconds which can be derived from the following information.

- 200 Nanoseconds/cycle = 5 million cycles/second

- Each cycle can carry an address (memory request) or
  for byte of data

- Thus, one cycle is used to request eight bytes of data
  (to be read or written), and two cycles are used to
  carry data (at four bytes/cycle).

- Five million cycles/second * 4 bytes/cycle = 20 million
  bytes/second

- 20 * 2/3 (1 of every 3 cycles is an address) = 13.3 million
  byte/second.[4]

The memory controller is the NEXUS used to interface the memory subsystem to the SBI. A system may have more than one memory controller as in the case of a two controller interleaved memory configuration.

The UNIBUS (UBUS) is a high speed asynchronous data system that allows communication between peripheral hardware and the VAX 11/780. The VAX 11/780 is capable of supporting 4 UBUS subsystems; one is standard with three more optional. The UBUS is connected to the SBI through a UBUS adapter (UBA) which performs priority arbitration among the devices on the UBUS. The primary functions of the UBA are to provide:

(1) Access to UBUS address space from the SBI

(2) Mapping of UBUS address to SBI addresses for UBUS direct memory access (DMA) transfers to system memory.

(3) Data transfer paths for UNIBUS device access to random SBI memory addresses and high speed transfer for devices that transfer to consecutive increasing address.

(4) UNIBUS interrupt fielding

(5) UNIBUS priority arbitration.

All of these services are completely transparent to UBUS users.

The address mapping function is necessary because the UBUS has only 18 data lines thus providing an apparent memory addressing capability of 2^{18} or 200 kilobytes. The UBA, however, provides the capability of mapping the UNIBUS addresses into SBI addresses so that the full memory of the system can be accessed. (Full system memory is 16 array boards of 256 kilobytes each for a total of 4 megabytes.)

The UBA accepts either of two forms of input from the UBUS: hardware generated interrupt or 'irect memory access transfer. Each device connected to the UBUS uses one of five priority levels for requesting bus service. The NonProcessor Request (NPR) is used when the device requests a direct access transfer to memory or some other device and does not require processor intervention. A Bus Request (BR) is used when the device wishes to interrupt the BPU for service. Such service might be a CPU directed data transfer or the informing of some error condition that exists at the perepheral. The NPR has the highest priority with four levels of BR following (BR7-BR4).

Since there are only five priority levels and more than one device
may be connected to a specific request level, if more than one device
makes the same request, the device that is electrically closest
to the UBS receives higher priority.

The Non Processor Request for direct memory access is a very
important feature of the UBUS subsystem. These DMA transfers can
be divided into two groups: random access of noncontiguous addresses
and sequential access of sequentially increasing address. For random
access, each UBUS transfer is made through the Direct Data Path
(DDP, one per UNIBUS) and is mapped into an SBI transfer. This
procedure allows only one word of data to be transferred during a
single SBI cycle. For devices capable of requesting sequential
access services, use is made of Buffered Data Path (BDP). Each
UNIBUS provides 15 such BDPs. The BDP stores the data so that four
UBUS transfers are performed for each SBI transfer.

The DDP must be used by devices not transferring to consecutive
increasing addresses or by devices that mix read and write functions.
The maximum throughput via the DDP is about 425 kilo words per
second for write operations and 316 kilo words per second for each
read operation. These rates will decrease as other SBI activity
increases.[4]

Maximum published throughput via the BDP is about 695 kilo words
per second for both read and write operations but actual expected
throughput rates are only 1.5 mega bits per second. This rate will
also decrease as other SBI activity increases.[1,5] BDP transfers are

restricted to block transfers where a block is defined as equal to
or greater than one byte. All transfers within the block must be
to consecutive and increasing addresses and all transfers must be
of the same function type (Read or Write).

The MASSBUS subsystem and the DR780 high perforfanc 32-bit
parallel interface will not be described in this report since an
understanding of their functional characteristics is not needed to
determine their relative impacts on the HYPER channel network. The
influence of both may be felt indirectly, however, since activity
on the MASSBUS or DR780 will translate to SBI activity which will
affect DDP and BDP transfer rates as described perviously.[4]

Likewise, the VAX CPU will not be described in detail but
several comments may be made about the CPU's effects cn throughput.
The CPU represents the most intensive traffic load on the memory
subsystem and hence on the SBI. Obviously if the processor is
engaged in computing, it will request data much more often than it
will write data. Fortunately the large memory cache (8 kilo bytes)
available to the CPU reduces the SBI traffic load considerably.

In terms of the SBI traffic, impact on the processor's speed, published
figures[4] indicate that in a system with two memory controllers, the
processor will be slowed about four percent per averaged megabyte
per second of I/O traffic. The impact of a single memory controller
is to slow the processor by a factor varying from two to four. Table
2 summarizes the DEC VAX 11/780 I/O characteristics.

TABLE 2. SUMMARY OF DEC VAX 11/780 DATA I/O CHARACTERISTICS

PROCESSOR   : 32 bit words

MAIN MEMORY

    Virtual Address Space : 4.3 billion bytes
    Cycle Time   : 800 nanoseconds per 64-bit read
                              1400 nanoseconds per 64-bit write

I/O UNIBUS Adapter

    Maximum UNIBUS I/O Rate: 1.5 Mb/sec through buffered data paths.
    Buffered Data Path   : 15 total, 8 byte buffer in each
                              695 K words/second for read operations
                              695 K words/second for write operations
                              Used for fast DMA transfers
    *Direct Data Path   : 425 K words/second for write operation
                              316 K words/second for read operation
                              Used for transfers to non-consecutive
                              memory locations.

    All data rates subject to degradation as traffic on SBI increases.
    (SBI allows communication interfaces between CPU, Memory, UNIBUS
    and MASSBUS.)

  ** Maximum aggregate throughputs on UNIBUS is only 1.5 Megabytes/
    second.

2.2.1.2 Perkin Elmer 3244

The Perkin Elmer (PE) 3240 series computer is a high throughput
machine with a 32 bit architecture. The HOSC currently uses two
PE 3244 machines with primary responsibilities as front end processors
(FEP) receiving real time data streams from the KSC firing room.

A block diagram of the 3240 model computer is shown in Figure 5.
Detailed information regarding the 3244 has not been obtained but a
brief description of the 3244 architectures follows.

The 3244 memory subsystem is organized into banks each capable
of handling 4 megabytes of addressable memory. Total system memory
ranges from 256 kilo bytes in one bank to a full system complement
of four 4 megabyte banks for a maximum of 16 megabytes of addressable
memory. All memory is connected to a common memory bus which consists
of two undirectional, asynchronuous, 32 bit busses. One bus is
dedicated to memory write functions and the other is dedicated to
memory read functions.

Input/Output is accomplished by up to five external communication
busses: one multiplexer bus for medium speed devices and up to
four high speed Direct Memory Access (DMA) busses. Each DMA bus
supports eight high speed bidirectional ports. Each DMA port is
controlled by a selector channel that controls and terminates
transfers through the CPU. This selector channel is controlled
through the multiplexer bus. Once the channel is activated, the
processor is released and is free to continue processing. Published
I/O transfer rates for the PE 3244 DMA bus indicate that transfer

Figure 5. Block Diagram of PE 3244 Computer

rates of up to 10 megabytes per second burst mode are possible for each DMA bus.[6] Table 3 summarizes the PE/3244 I/O characteristics.

2.2.1.3 Perkin Elmer 8/32c

Detailed information about the 8/32 computer has not been obtained, but conceptually, the 8/32 is a machine similar in architecture to the 3244. A significant difference is that the 8/32 is capable of supporting only one DMA bus. This DMA operates in a burst mode capable of transferring 6 megabytes per second. The 8/32 will allow configuration with a buffered selector channel that accomplish the 6 MB/s rate by transferring the data in 14 half-word blocks.[7] Table 4 summarizes the estimated PE 8/32c I/O characteristics.

2.2.2 NSC HYPER channel

The Network System Corporation HYPER channel (HC) is a broadband local area communication network supporting data transmissions between network users at a rate of 50 megabyte per second. The HYPER channel network (HCN) serves to interface and interconnect various sizes of mainframe computers of differing manufacturers (e.g., UNIVAC, DEC, CRAY, PERKIN ELMER) with other peripherals such as data entry terminal card readers, printers, mass storage devices and other networks. Communication is provided over a passive 75 ohm coaxial cable called a trunk.

TABLE 3. SUMMARY OF PERKIN ELMER 3244 I/O CHARACTERISTICS

PROCESSOR   : 32 bit/word

MAIN MEMORY

      Virtual Address Space: 4 Megabytes
   Basic Memory Access Time: 500 nanoseconds

DMA BUS DATA TRANSFER RATE: 10 Megabytes/second-burst mode
                           Maximum of 4 DMA busses can be
                                supported.

TABLE 4.   SUMMARY OF PERKIN ELMER 8/32 I/O CHARACTERISTICS

PROCESSOR   : 32 bit/word

DMA BUS DATA TRANSFER RATE: 6 Megabytes/second by transferring
                              data in 14 half-word blocks.
                              Only one DMA can be supported.

Host computers gain access to the network trunk through hardware
interfaces called processor adapters; unintelligent peripherals through
device adapters. Network to network connection are accomplished with
a link adapter which supports not only communication with standard
transmission lines but also with microwave frequency RF links. Each
network adapter may be connected to as many as four separate trunks
and provides the service of trunk selection, trunk access, establishment
of adapter to adapter virtual circuits and also provides user-to-adapter
protocols. Network adapters contend for trunk control using a Carrier
Sense Multiple Access scheme with prioritized staggered delays.[9]

The heart of the network is the A400 Adapter. The A400 is a
microcomputer controlled interface device that allows up to 4 mini-
computers of the same or mixed manufacturer types to transmit and
receive data over the HYPER channel network. (All four trunk port
may be connected to four channels of the same minicomputer.) The
A400 provides a buffered interface between the trunk and the adapter.
Some of this buffer is used to provide parallel to serial data stream
conversion for host to trunk transmissions and serial to parallel
conversion for trunk to host transmissions.

Each A400 adapter is composed of

- a 16 bit microprocessor with 4906 words

    of read only memory.

- a storage section consisting of

    1024 8-bit bytes of control memory with

        odd parity

    4096 8-bit bytes of control buffer with

        odd parity

16 working registers

16 trunk registers

256 extension register

. one trunk interface.

The adapter can be expanded to contain

. 4 trunk interfaces

. 8192 8-bit bytes of buffer memory

. 1024 8 bit bytes of code conversion memory.

Additionally, the adapter has a peripheral device interface that provides
a standard interface between the internal busses of the minicomputer
and the A400. The peripheral interface adapter is separated from, but
connected with ribbon cables to, the nucleus adapter which provides the
hardware resources such as the microprocessor and memory register.[8,10]
(See Figure 6)

To perform an operation on the network, the minicomputer loads
the necessary parameters into the internal registers on the interface
and requests the adapter to perform the indicated functions. Whenever
an adapter is not performing a function, it scans all attached ports
for a request to perform a function. When a function request is
detected, the adapter suspends scanning and initiates the execution
of the function. The flow diagram of Figure 7 illustrates the
handshaking between the A400 and host processor when data transfers
are initiated. Notice that the host processor initiates all actions
of the adapter. (A compilation of functions that can be accomplished
by the A400 is illustrated in Table 5.)[8]

Figure 6. NSC HYPERChannel Adapter block diagram.

NOTES:

1. The A400 Adapter supports the maximum host processor data transfer rates.
   Typical Values:
   PE 3244 - 10 Mbytes/sec.
   PE 8/32c - 6 Mbytes/sec in Burst Mode
   DEC UNIBUS - 1.5 Megabytes/sec through Buffered Data paths.

2. Microprocessor (logical) Interface consists of firmware (PROMS) to direct and control device transmissions, trunk selections, trunk transmissions and Assembly/Disassembly.

3. Trunk side consists of I/o Buffering, serial/Parallel Conversion, Checksum generator and checker, and Trunk Transceiver.

4. Device Interface side consists of I/o Extension Registers and the DMA Controller.

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GO
FROM
PROCESSOR?   N   Y

INTERPRET
FUNCTION ON
DATA OUT BUS

Host places 16 bits of
data on DATA OUT bus and
issues a GO pulse. Host
also disables the READY
line which stays inactive
until function has been
executed.

A function from host
initiates every adapter
operation.

PROCESS
NONTRANSFER
FUNCTION   N

DATA
TRANSMISSION
REQUIRED
?   Y

INPUT
OR
OUTPUT

OUTPUT
HOST TO ADAPTER

INPUT
ADAPTER TO HOST

C1
SET

C1
CLEARED

CYCLE
REQUEST
OUT

DATA PLACED
ON DATA IN
BUS

Host responds by
putting data on DATA
OUT bus and sending END
of cycle.

CYCLE
REQUEST
INPUT

END
CYCLE
R'CVED?   N   Y

Informs host that
valid exists on
bus. Host then
accepts data
and sends END
CYCLE.

END
CYCLE
R'CVED?   N   Y

INPUT
DATA
ON BUS

Accept data on bus
and transfer into
registers or buffers
as required.

TRANSFER
MORE
DATA
?   N   Y

Figure 7. Host to A400 Adapter Data Exchange

TABLE 5.   A400 ADAPTER FUNCTION DESCRIPTION

CODE	FUNCTION
04	Transmit message
08	Transmit data
0C	Transmit last data
10	Transmit local message
24	Input message
28	Input data
40	Status
50	Dump extension register
60	Mark down port 0
64	Mark down port 1
68	Mark down port 2
6C	Mark down port 3
70	Mark down port 0 and re-route messages
74	Mark down port 1 and re-route messages
78	Mark down port 2 and re-route messages
7C	Mark down port 3 and re-route messages
A0	Read statistics
A4	Read and clear statistics
C0	Set test
C4	Set address and length
C8	Write buffer
CC	Read buffer
E0	Clear adapter
E4	End operation
E6	Clear and wait for message
E8	Wait for message.

Data can be transferred from host to adapter in two different modes: direct memory access (DMA) and register mode. In the DMA mode, the adapter uses an alternating buffer scheme. The adapter accepts data from the device into buffer memory. When the buffer is half full, trunk transmission of that amount of data is initiated as, the other half of the buffer is being filled. This filling and sending is continued until all data has been transferred. All DMA transfers are through the extension registers and are initiated by the adapter microprocessor and controlled by the adapter hardware.

In the register mode, data movement is also between the device interface and the nucleus adapter but the DMA controls are not used. These data transfers are also through the extension register but initiated and controlled by the microprocessor.

Data transfers from adapter to adapter are accomplished by the trunk interface. The trunk interface consists of a passive coaxial cable that transmits data serially between two adapters. Each trunk can have up to 64 drops depending on the length of the trunk cable and its transmission qualities.

Transmissions on a trunk are initiated and monitored by the trunk driver which is a microcode program stored in the adapter PROMs. The extension register and the trunk registers support the PROM trunk driver. When an adapter is ready to transmit, it must first contend for use of the trunk. The method for contention is called contention allocation. It is so called because the trunk is allocated to an adapter based on the adapter's need to transmit.

The contention process can be summarized as follows. The adapter first just attempts to transmit on the trunk. If the trunk is busy, the transmitter is disabled. When the trunk becomes free, a fixed delay is initiated by the adapter. This prevents the adapter from transmitting until the receiving party of the most recent transmission has had time to receive a response frame. Upon expiration of the fixed delay, another delay called the priority delay is initiated. This delay is different for each adapter and provides a unique time slot for each adapter on the trunk. Annother delay, called end delay, is provided following the fixed delay. This delay is provided to insure that all adapters with higher priority have first access to the trunk. Obviously, with this trunk allocation scheme, higher priority adapters can dominate the trunk. To prevent this, each adapter has a flip flop in it that is known as the wait flip flop. This flip flop is set when the adapter transmits and is cleared when an end delay is signalled. This flip flop is intended to provide a more equitable contention environment. Although all adapters are equipped with wait flip flops, they may be disabled to provide assured trunk access.[9,10] Figure 8 shows the flow of the wait algorithm.

Upon gaining access to the trunk, either a function message or data can be transmitted in trunk frames. When a frame is transmitted all adapters receive the frame. The adapter compares the received adapter access code which is part of the frame header with its own code which can be set by thumblwheel switches in the adapter. If and only if the codes match can the communication be accepted. (A zero in the receiving adapter code represents a "don't care" condition and

ORIGINAL PAGE IS
OF POOR QUALITY

DATA TO TRANSMIT ON TRUNK? — N / Y

ATTEMPT
TO
TRANSMIT

TRUNK
BUSY — N → TRANSMIT / Y

TRANSMIT
LINE
DISABLED

INITIATE
FIXED
DELAY

FIXED
DELAY
EXPIRED? — N / Y

Fixed delay prevents adapter
from transmitting until the
receiving party of ongoing
transmission has sent
a trunk response frame.

INITIATE
PRIORITY
DELAY

PRIORITY
DELAY
EXPIRED? — N / Y

Priority delay provides
unique time slot for
each adapter on trunk.

WAIT
FLIP-FLOP
ENABLED? — N / Y

Wait fused to keep higher priority
adapters from dominating the
trunk may be disabled or
enabled.

INITIATE
END
DELAY

All other
adapters have
free access to
trunk during this

END
DELAY
EXPIRED? — N / Y

Figure 8.   Trunk Contention Delay Algorithm

the receiving adapter will accept any character in that code position.)

The receiving adapter responds to the receipt of a trunk transmission with a trunk response frame. This notifies the sending adapter of the status of the received message. Every transmission frame requires the receipt of a response frame or the sending adapter will time out and retry the transmission. This process will be repeated 256 times. If unsuccessful at transmitting the message, the adapter will terminate the operation and record some status bits for the host in the adapter extension registers.[10]

2.2.3 Other HOSC Components

In addition to the computer resources are several other devices in the HOSC. Currently these other devices act as peripherals to the processors on the HYPER channel network and consequently do not directly affect traffic on the network. Indirectly, they represent overhead processor activity and thus slow traffic throughput on the processor I/O busses. These devices will include a Gandalf solid state switcing matrix that acts to interface the MIPS consoles through VAX4. Also included in the peripherals are various strip recorders ⌐⌐ three twelve-channel Genesco digital televisions that interface the engineering consoles through STS Primary (PE 3244), STS Backup (PE 8/32c) and Spacelab 8/32. No further descriptions of these devices are currently available.

3.0 HOSC ANALYSIS RESULTS

The HOSC system analysis initiated with a study of the system componente, the computers, the HYPER channel network, the data flow activity of each device and the input-output characteristics of each device. The system operation is statistical in nature and, although a mathematical analysis is possible, it is not feasible to make such an analysis with much fidelity. Rather a simulation model that emulates the HOSC system with good fidelity can be used to achieve information concerning average bus traffic, average waiting time, collision frequency and maximum waiting times. Furthermore, these parameters can be investigated as a function of HOSC system configuration, input-output variations, and data file dump requirements.

The development of a simulation model with good fidelity has been accomplished. The HOSC system has been modeled with three different program simulations and these three algorithms have been compared against each other. The purpose in using three algorithms was to insure validity of the simulation results, a necessity due to the lack of sufficient system statistics to validate a single simulation algorithm. The three algorithms are similar, but have been programmed in BASIC, PASCAL and SLAM.

BASIC is an engineering oriented language not at all unlike FORTRAN. This simulation program is the main program. The program is listed in Appendix I.

Although many simulation runs were made with simple system configurations that allowed the simulation algorithm to be verified, there is no need to present those in this report. The monthly reports

document these earlier runs and the development of the algorithm.
Rather it suffices to illustrate the simulation of the HOSC system
as it is projected in configuration in Summer 1983.

3.1   Typical Basic Algorithm Information Printouts

Figure 9 depicts the HOSC simulation configuration which is
documented in this report. This configuration is perhaps more com-
plex than the actual system configuration for the present, but it
is the type of configuration that is desired in the near future.
Not all devices are transmitters of data in this system configuration.
The A400 labeled port 4 only receives data transmitted on the HYPER
channel bus. Other devices receive outside data and transmit and
received data over the HYPER channel bus. This system configuration
was devised at a meeting between this investigator and NASA/MSFC
HOSC personnel on March 9, 1983, and is typical of the configurations
to be utilized for HOSC applications in the near future.

In order to determine the number of simulation runs necessary
to produce representative statistics and to let the system algorithm
achieve steady state, as would occur in the actual system, several
runs with the same system configuration parameters but with varying
numbers of data transfers were made and the statistics compared.

Figures 10 and 11 illustrate the program printout that depicts
the system configuration of figure 9. The # of bytes accumulated
refers to the number of bytes which a particular device will accum-
ulate refers to the number of bytes which a particular device will
accumulate from a source before it transmits that data to the appro-
proiate destination. As may be noted in Figure 10, there is a

6.25 MBYTE/SEC

6.25 MBYTE/SEC

A400 PORT 1 — DEC 11/24 REMOTE PERIPHAL DEVICES (111) .5MBYTE/SEC

A400 PORT 2 — VAX SPACE TELESCOPE (211), VAX SOFTWARE DEVELOPMENT (221) — .5MBYTE/SEC / .5MBYTE/SEC / .5MBYTE/SEC

A400 PORT 3 — VAX MIPS PRIME (311), VAX MIPS OCCUP (321), PE3244 FEP (0/2 DATA) (331) — .5MBYTE/ .5MBYTE/SEC / .5MBYTE/ .5MBYTE/SEC / 3.3MBYTE/ SEC

A400 PORT 4 — PE3244 STS PRIME (411), PE A/3C SPACE LAB PRIME (421), PE3244 SPACE LAB DUMP (431) — 3.3MBYTE/ 1.2MBYTE/SEC / 1.2MBYTE/1.2MBYTE/ SEC

		DATA ARRIVAL RATE KBYTE/SEC	DATA TRANSFER BLOCK SIZE KBYTES/TRANSMISSION
(111)		15.0	2.0
(211)		4.0	4.0
(221)		6.4	6.4
(311)		1.0	.512
(321)		1.0	.512
(331)		.625	.625
(411)		0	2.0
(421)		0	2.0
(431)		0	2.0

DATA FILE DUMP	TIME BETWEEN DUMPS	DATA BLOCK KBYTES
DEC11/24 to STS PRIME (PE3244)	12 SEC	64 KBYTES

SOURCE/DESTINATION	PROBABILITIES
111-311	.7
111-321	.3
211-431	1.0
221-421	1.0
311-321	.98
311-221	.01
311-211	.01
321-311	.98
321-221	.01
321-211	.01
331-421	1.0

Figure 9. HOSC Simulation Configuration

OF HYPERCHANNEL PORTS = 4

OF DEVICES FOR PORT 1 = 1
OF DEVICES FOR PORT 2 = 2
OF DEVICES FOR PORT 3 = 3
OF DEVICES FOR PORT 4 = 3

OF SOURCES FOR PORT 1 DEVICE 1 = 1
OF SOURCES FOR PORT 2 DEVICE 1 = 1
OF SOURCES FOR PORT 2 DEVICE 2 = 1
OF SOURCES FOR PORT 3 DEVICE 1 = 1
OF SOURCES FOR PORT 3 DEVICE 2 = 1
OF SOURCES FOR PORT 3 DEVICE 3 = 1
OF SOURCES FOR PORT 4 DEVICE 1 = 1
OF SOURCES FOR PORT 4 DEVICE 2 = 1
OF SOURCES FOR PORT 4 DEVICE 3 = 1

PORT,DEVICE,SOURCE			AVERAGE ARRIVAL RATE	# OF BYTES ACCUMULATED
1	1	1	15000	2048
2	1	1	4000	4000
2	2	1	6400	6400
3	1	1	1000	512
3	2	1	1000	512
3	3	1	625	625
4	1	1	0	2000
4	2	1	0	2000
4	3	1	0	2000

CU-CM DATA FILE DUMP	BYTES TO BE BUFFED	TIME BETWEEN DUMPS (IN SECONDS)
1141	64000	12

Figure 10. System Configuration Parameters for 1333 Data Transfer Simulation.

WAIT TIME OF PORT 1 BEFORE TRANSMISSION REQUEST (IN EVENT OF A COLLISION)
.000001
WAIT TIME OF PORT 2 BEFORE TRANSMISSION REQUEST (IN EVENT OF A COLLISION)
.000002
WAIT TIME OF PORT 3 BEFORE TRANSMISSION REQUEST (IN EVENT OF A COLLISION)
.000003
WAIT TIME OF PORT 4 BEFORE TRANSMISSION REQUEST (IN EVENT OF A COLLISION)
.000004

CHANNEL SETUP AND RELEASE TIME = .000025

CHANNEL DATA TRANSFER RATE = 6250000

PORT.DEVICE	TRANSFER RATE	LOAD TIMES
1 1	500000	.000002
2 1 - 2	500000	.000002
2 1 - 2	500000	.000002
3 1 - 2	500000	.000002
3 2 - 3	500000	.000002
3 3	3300000	3.0303030303E-7
4 1 - 2	3300000	3.0303030303E-7
4 2	1200000	8.3333333333E-7
4 3	1200000	8.3333333333E-7

COMBINATIONS (IJK - LMN)	PROBABILITY	TIME TO TRANSMIT Q(IJK) BYTES (IJK - LMN)
111311	.7	.004441
111321	.3	.004441
211431	1	.008345
221421	1	.013145
311321	.98	.001369
311221	.01	.001369
311211	.01	.001369
321311	.98	.001369
321221	.01	.001369
321211	.01	.001369
331421	1	8.6583333333E-4

Figure 11. System Configuration Parameters for 1333 Data Transfers.

data file du..? of 64,000 bytes every i2 seconds as would be typical
of a data file refresh operation.

The channel setup and release time is a parameter used to
allow the HYPER channel to establish a transmission link and then
to release the link after data transfer is complete.

As data is transferred across the system, each port vies for
the bus in a contention scheme described in Section 2. Occasionally
the ports will collide trying to transmit simultaneously. In Figures
12 and 13, a printout record of the results of a collision is illus-
trated. These printout records allow the operator to ensure the
collision algorithm is working properly. As may be noted, 331 and
111 incurred a collision and 111 retransmitted first, since its
assigned waiting time is less than 331.

Every time a data transfer occurs between two devices on the
same port, the HYPER channel bus is not utilized and thus it is
free for other transmissions except to the port involved in an inter-
port data transfer. Figure 14 illustrates a printout record of an
inter device data transfer. Figure 14 also illustrates a record of a
data file dump.

The statistical printout of a simulation run is illustrated in
Fugure 15. This run had 1333 data transfers and over three million
bytes transferred.

3.2   Results of A Simulation Run

Inspection of Figure 15 will illustrate the information garnered
by a simulation run. The items of interest are the bus busy time,
collision frequency of each source, the average waiting time, the
longest waiting time and the relative activity of each source.

COLLISION OCCURRED BETWEEN ... AND ...

ITERATION NUMBER 386

PROBABILITY ...
RANDOM NUMBER .8645370057222
PROBABILITY 1

ESTIMATION 321

PORT,DEVICE,SOURCE ... TOTAL TIME GONE BY SINCE LAST TRANSMISSION
.135719166711
.48061499984
.66846049377
.30145459979
.30145249997
1.000001
999999
999999
999999

PORT,DEVICE,SOURCE ... REMAINING TIME TO TRANSMIT (NORMALIZED FASHION)
.00081416662
.20195850691
.33153950062
.21054750021
.21054750021
-.000001
999999
999999
999999

COLLISION NUMBER 3
DATA TRANSFER .004445

Figure 12. Typical Printout When Data Transfer Collision Occurs.

PORT,DEVICE,SOURCE   ACCUMULATED WAITING TIMES SINCE THE LAST TRANSMISSION

```
1     1   1                          0
1     2   1                          .50250249999984
1     2   1                          .672901499997?
2     2   1                          .50589349999979
2     3   1                          .30589349999979
3     3   1                          1.004442
4     3   1                          999995
4     3   1                          999995
4     4   1                          999995
```

DATA TRANSFER COMPLETED: TOTAL TIME GONE BY 28.340377331

PORT,DEVICE,SOURCE   REMAINING TIME TO TRANSMIT (NORMALIZED FASHION)

```
1     1   1                          .13653333333
1     2   1                          .19749750000016
1     2   1                          .37098500023
2     2   1                          .20610650002?
2     3   1                          .20610650002?
3     3   1                          -.004442
4     3   1                          999999
4     3   1                          999995
4     4   1                          999995
                                     33?
```

NEXT TRANSMISSION REQUEST BY 331 STARTS TO TRANSMIT 28.340377331
TOTAL TIME THAT WILL BE GONE BY WHEN 331 STARTS TO TRANSMIT 28.340377331

ITERATION NUMBER 387

PROBABILITY 1
RANDOM NUMBER .608213251646

ESTIMATION 421

Figure 13. Typical Printout When Data Transfer Collision Occurs (Continued).

TRANSMISSION ON SAME A400 SOURCE/DEST = 321311
NO COLLISION OCCURED

SOURCE 1 . 1   DUMPED TO DESTINATION 4 . 1   64000 BYTES OF DATA
TOTAL TIME GONE BY (BEFORE THE DUMP) 96.44314099909
TOTAL TIME GONE BY (AFTER THE DUMP) 96.5764859909

TRANSMISSION ON SAME A400 SOURCE/DEST = 311321
NO COLLISION OCCURED
TRANSMISSION ON SAME A400 SOURCE/DEST = 321311
NO COLLISION OCCURED

Figure 14. Typical Printout for Data File Dump and Inter Source Data Transfers.

Figure 15. Statistical Summary of 1333 Data Transfer Simulation.

Percent Bus Busy Time = 6.34%

PORT,	DEVICE,	SOURCE	AVG. WAIT TIME %	LONGEST WAIT %
1	1	1	27.18%	94.00%
2	1	1	4.11%	12.84%
2	2	1	1.72%	4.51%
3	1	1	10.88%	25.07%
3	2	1	1.22%	25.35%
3	3	1	3.01%	10.17%

Number of Data Transfer Collisions = 6 Collisions

Number of Data File Dumps (11 to 41) = 8 (64,000 Bytes Each)

Bytes Transferred by Data File Dump = 512,000 Bytes

Bytes Transferred Source to Destination = 2,616,399 Bytes

Total Bytes Transferred = 3,128,399 Bytes

For the 1333 data transfer simulation with data file dump of 64,000 bytes every 12 seconds the parameters of interest are depected in the figure. Everything points to a satisfactory operation at this point with one notable exception, the longest waiting time. This Figure is -128.345 milliseconds (the negative sign indicates waiting time) for P.D.S. 111 which has an average time between transmission requests of 136.533 milliseconds (# of bytes accumulated divided by the average arrival rate of the bytes. The data is drawn from Figure 10.)

This waiting time amounts to 94% of the average time between transmission requests for P.D.S. 111 and serves a warning that P.D.S. 111 is on the verge of being overloaded. This may be alleviated by several means--changing the number of bytes to be accumulated before making a transmission request or by changing the data file dump time interval. In Section 3.4, this is discussed more fully.

3.3   Comparison of BASIC, PASCAL and SLAM Programs

Appendix II contains a listing of the PASCAL program and summary sheet for the HOSC simulation. The SLAM program listing is not included since NASA/MSFC does not carry SLAM software support. The three algorithms are compared in a broad sense in Table 6. The three algorithms were run for comparison purposes using 500 data transfers as the benchmark. The total bus time, bus utilization percentage, number of bytes transferred all compare very favorably. The number of collisions incurred vary due to differences in the collision algorithms used in the programs which were programmed by three different programmers as a check on the algorithms. The

TABLE 6

COMPARISONS OF BASIC PASCAL AND SLAM PROGRAMS

NO DATA FILE DUMPS SIMULATED

	BASIC	PASCAL	SLAM
Total Transmissions	500	500	500
Elapsed Time on Bus (Seconds)	36.08	36.44	35.24
Collisions	8	29	19
Waits	N.T.	83	36
Bus Utilization	5.82%	4.69%	6.02%
Bytes Transferred	979,795	987,360	985,939

N.T. = Not Tabulated

The algorithms programmed all have the following features:

1. Allows up to 9 A400 adaptors

2. Allows up to 9 computer devices per A400 adaptor

3. Allows up to 9 data sources per device

4. Allows each device to transfer large block of data on a periodic basis such as for CRT data base refresh

5. Allows assignment of individual waiting times to be assigned to each A400 in event of a collision

6. Allows the shortest assigned waiting time A400 to retry a transmission in the event of a collision

7. If a data transfer occurs between two devices on the same A400 (Inter A400 data transfer) it allows this to occur without tying up the bus

8. Allows for individual source data arrival rates

9. Allows for individual source data buffer sizes (relates to time between transmission requests)

10. Allows for individual device to A400 I/O data rates.

The results indicate no major discrepancies lie in the HOSC system model used for the algorithm development. The BASIC program has been emphasized since it is more transportable than SLAM or PASCAL. However, for a next generation simulation model, PASCAL will be contructed in a user friendly format since it has some features which make it suitable for this type of simulation.

3.4   Conclusions

Results of a fair run simulation using the configuration of Figure 9 has been tabulated in Table 7. The purpose of this comparison was to determine:

TABLE 7

COMPARISON OF FOUR SIMULATION RUNS
(BASIC PROGRAM)

P.D.S.	TTNR(MS)	LONGEST WAITING TIME (MS, % TTNR)					AVERAGE WAITING TIME (%)					DMS BEST TIME (%)				
		RUN A	RUN B	RUN C	RUN D	RUN E	RUN A	RUN B	RUN C	RUN D	RUN E	RUN A	RUN B	RUN C	RUN D	RUN E
1 1 1	136	128 (94%)	128 (94%)	256 (188%)	128 (94%)	8 (6%)	29	27	45	29	39					
2 1 1	1000	128 (13%)	128 (13%)	118 (11.8%)	19 (2%)	4 (.4%)	2.8	4.1	4.8	1.7	.22	6.75%	6.3%	6.32%	6.35%	5.9%
2 2 1	1000	45 (5%)	45 (5%)	8.4 (.84%)	8 (.8%)	9 (1%)	1.5	1.7	.35	.47	.42					
3 1 1	512	129 (25%)	128 (25%)	256 (50%)	116 (23%)	5 (1%)	1.9	10.9	11.5	1.6	.21					
3 2 1	512	128 (25%)	130 (26%)	258 (50%)	116 (23%)	4 (1%)	3.2	1.2	.85	1.2	.57					
3 3 1	1000	101 (10%)	101 (10%)	202 (20%)	101 (10%)	13 (1.3%)	3.0	3.0	2.8	3.2	.81					

P.D.S - PORT, DEVICE, SOURCE

Average Waiting Time is expressed as percent of TTNR

TTNR = Time to Next Transmission Request = Time Between Data Transfer Requests

Number of Collisions: RUN A - 10; RUN B - 6; RUN C - 14; RUN D - 3; RUN E - 3

RUN A 1500 data transfers, Data file dump once every 12 seconds, 64,000 bytes each dump
RUN B 1333 data transfers, Data file dump once every 12 seconds, 64,000 bytes each dump
RUN C 1000 data transfers, Data file dump once every 12 seconds, 128,000 bytes each dump
RUN D   500 data transfers, Data file dump once every 12 seconds, 64,000 bytes each dump
RUN E   500 data transfers, Data file dump once every 120 seconds, 64,000 bytes each dump
       (For a 500 iteration run time of 36 milliseconds no data file dump occurs).

a) The number of iterations necessary to produce consistent results.

b) Determine the effects of varying the data file dump interval.

Since each simulation run uses random number generators as part of the program, it should not be surprising to see small differences in the output summary statistics. Indeed two runs of the same configuration with the same number of iterations will produce slightly different results. This is completely expected and does not reduce the value of the results at all.

The results tabulated in Table 7 indicate that the system performs as desired with one exception. The data file dump. Every 24 seconds, Run C, creates a waiting time of 256 milliseconds for P.D.S. 111, which is 188% of the time between transmission requests for source P.D.S. 111. The impact of these results from a realization that 100% waiting time for a source would mean that source has been waiting for an opportunity to transmit for such a long time that it now has three transmission requests rather than one. It is obvious from the data in Table 7 that large data file dumps will tend to create a log jam for devices with active external data sources. These external data sources may not be extinguishable; hence, the need to provide sufficient data storage in the device to hold incoming data during a large data file dump is paramount.

An analytical feeling for this problem is easily derived. Any source with a data file dump will experience an external source transmission request whenever the data file dump time exceeds the total time between transmission requests for that source. In the

configuration of Figure 9, we have a data file dump from P.D. 11 to
P.D. 41. The I/O rate for P.D. 11 is 500 K Bytes per second and the
I/O rate for P.D. 41 is 3.30 M Bytes per second. The channel trans-
fer rate is 6.25 M Bytes per second so that data file dump will take
a total time equal to the channel setup release time plus the time to
dump X Bytes at the slowest I/O rate or for our configurations the
data file dump time (DFDT) is

$$DFDT = 25 \ \mu sec + X(2 \ \mu sec/Byte) \ .$$

For 64,000 Bytes DFDT = 128 msec and
for 128,000 Bytes DFDT = 256 msec.

In fact whenever the DFDT exceeds the fastest source average time to
transmission request time a problem will definitely arise. For the
example where the number of bytes in a data file dump exceeds

$$\frac{\text{Number of Bytes}}{\text{In Data File Dump}} = \frac{126.533 - .025}{2 \times 10^{-3}} = 68254 \ \text{Bytes}.$$

the fastest source will possibly incur two transmission requests.

There are several ways to correct this situation:

a)   Increase the buffer size of the source so it can store
more than two full sets of data between transmission
opportunities. This is a viable option since source
P.D.S. 111 is the most active with highest outside data
arrival rate and only 2048 bytes to be accumulated between
transmission requests.

b) Perform data file dumps more often but transfer proportionally less bytes per dump thereby reducing any sources waiting time. This may not be a viable option due to the lack of data file data being ready in a somewhat steady occurrance rate. Also this would require a data file storage medium at the destinations; however, this is usually the case.

c) Break up the data file dump by transmitting it in smaller packets. That is rather than 64,000 bytes in a steady stream for a short time once every 12 seconds, transmit 8,000 bytes, break and release channel to allow another user but request transmission rights immediately and repeat for 8 times. This would transfer the data in almost the same time as sending all 64,000 bytes while allowing the active devices a chance to clear their stored data.

All the above options could be accomplished through software programming of the source device P.D. 11; thus, it is a HOSC system operators choice of which method to utilize.

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APPENDIX I

BASIC SIMULATION ALGORITHM PROGRAM

A listing of the BASIC simulation algorithm program is presented in this appendix. The program contains plentiful comments and is user oriented, with prompts and options displayed on the interactive screen. The BASIC language is common to many machines; however, the input output commands are usually particular to a single machine, in this case the HP-87 system.

```
*************************
*  PROGRAM:     HDSC           *
*  AUTHOR:      DR. FRANK INGELS   *
*  PROGRAMMER:  TERESA BENNET      *
*  DATE:        MAY 12,1983        *
*************************
* I -- # OF PORTS                              J=3
* IJ -- # OF DEVICES FOR EACH PORT             J=6
* IJK -- # OF SOURCES FOR EACH DEVICE          K<=3
* LA(IJ,K) --  AVERAGE ARRIVAL RATE OF DATA TO SOURCE
* NU(IJ,K) --  # OF BYTES ACCUMULATED BY SOURCE K, DEVICE J, PORT I
*              BEFORE DEVICE J REQUESTS A TRANSMISSION
* TSR --  CHANNEL SETUP AND RELEASE TIME
* CR  --  CHANNEL DATA TRANSFER RATE
* PR(IJK,LMN) -- PROBABILITY THAT SOURCE IJK WILL TRANSMIT DATA TO LMN
* BBT = BUS BUSY TIME
* BEGIN PROGRAM EXECUTION
* INTEGER I,J,K,L,M,N,O
BBT=0 : CH1=999999 : CH2=999999 : CLINS="N" : CLNS="N" : EOS="N" : HY$="Y"
DIM PDS(200),PRO(200),T(200),TIMESTT(200),DT(200),BYTES(20),TIM(20),BTFL(20)
WT(20)
CLEAR : DISP TAB (20);"MENU" : DISP : DISP "1  --  RECALL AN EXISTING DATA F
LE"
DISP "2  -- EXECUTE PROGRAM WITHOUT THE FILE OPTION"
DISP "3  -- CREATE A NEW DATA FILE AND EXECUTE PROGRAM"
DISP : DISP "ENTER YOUR SELECTION ";: INPUT AN
IF AN<1 OR AN>3 THEN 210
PRINTER IS 701
DISP "  ": DISP "INDICATE THE NUMBER OF PROGRAM ITERATIONS ";: INPUT NUMIER

ON AN GOTO 250,276,290
DISP : DISP "ENTER THE DATA FILE NAME ";: INPUT DFNAME$
IF AN=1 THEN GETDATA=999 : GOTO 1350 ELSE GETDATA=888
* DATA ENTRY ROUTINE   (IF AN=2 OR AN=3)
* LINES 310-1330
*************************
CLEAR : DISP "PLEASE ENTER THE FOLLOWING DATA ITEMS:" : DISP
DISP "# OF HYPERCHANNEL PORTS           ";: INPUT HY
FOR I=1 TO HY : DISP "# OF DEVICES FOR PORT ";I;" ";: INPUT DV(I): NEXT I :
: CLEAR
FOR K=1 TO DV(I)
DISP "# OF SOURCES FOR PORT ";I;" DEVICE ";K;: INPUT SRC(I,K)
NEXT K : I=I+1 : IF I<= HY THEN 340 ELSE I=0
```

```
370 I=I+1 @ CLEAR @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ CLEAR
380 DISP " FOR "I;" DEVICE ".J;" SOURCE ";J @ DISP @ DISP
390 DISP "AVERAGE ARRIVAL RATE ";: INPUT LA(J,K)
400 DISP "# OF BYTES ACCUMULATED BEFORE A TRANSMISSION REQUEST IS TO BE MADE BY
EVICE ";J;: DISP "(VALUE ASSIGNED 500 BYTES UNLESS";
410 QS="": QQ(J,K)=500 @ DISP " OTHERWISE SECIFIED";: INPUT QS
420 IF QS <> "" THEN QQ(J,K)=VAL (QS)
430 NEXT K @ NEXT J @ ON I GOSUB 450,490,530,570,610,650,690,730,770
440 IF I=HY THEN 810 ELSE GOTO 370
450 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA1(J,K)=LA(J,K) @ Q1(J,K).
)=QQ(J,K) @ QQ(J,K)=0
460 IF LA1(J,K)=0 THEN ATR1(J,K)=999999 ELSE ATR1(J,K)=Q1(J,K)/LA1(J,K)
470 NEXT K @ NEXT J @ RETURN
480 LA=LA1(J,K) @ QQ=Q1(J,K) @ ATR=ATR1(J,K) @ RETURN
490 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA2(J,K)=LA(J,K) @ Q2(J,K).
)=QQ(J,K) @ QQ(J,K)=0
500 IF LA2(J,K)=0 THEN ATR2(J,K)=999999 ELSE ATR2(J,K)=Q2(J,K)/LA2(J,K)
510 NEXT K @ NEXT J @ RETURN
520 LA=LA2(J,K) @ QQ=Q2(J,K) @ ATR=ATR2(J,K) @ RETURN
530 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA3(J,K)=LA(J,K) @ Q3(J,K).
)=QQ(J,K) @ QQ(J,K)=0
540 IF LA3(J,K)=0 THEN ATR3(J,K)=999999 ELSE ATR3(J,K)=Q3(J,K)/LA3(J,K)
550 NEXT K @ NEXT J @ RETURN
560 LA=LA3(J,K) @ QQ=Q3(J,K) @ ATR=ATR3(J,K) @ RETURN
570 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA4(J,K)=LA(J,K) @ Q4(J,K).
)=QQ(J,K) @ QQ(J,K)=0
580 IF LA4(J,K)=0 THEN ATR4(J,K)=999999 ELSE ATR4(J,K)=Q4(J,K)/LA4(J,K)
590 NEXT K @ NEXT J @ RETURN
600 LA=LA4(J,K) @ QQ=Q4(J,K) @ ATR=ATR4(J,K) @ RETURN
610 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA5(J,K)=LA(J,K) @ Q5(J,K).
)=QQ(J,K) @ QQ(J,K)=0
620 IF LA5(J,K)=0 THEN ATR5(J,K)=999999 ELSE ATR5(J,K)=Q5(J,K)/LA5(J,K)
630 NEXT K @ NEXT J @ RETURN
640 LA=LA5(J,K) @ QQ=Q5(J,K) @ ATR=ATR5(J,K) @ RETURN
650 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA6(J,K)=LA(J,K) @ Q6(J,K).
)=QQ(J,K) @ QQ(J,K)=0
660 IF LA6(J,K)=0 THEN ATR6(J,K)=999999 ELSE ATR6(J,K)=Q6(J,K)/LA6(J,K)
670 NEXT K @ NEXT J @ RETURN
680 LA=LA6(J,K) @ QQ=Q6(J,K) @ ATR=ATR6(J,K) @ RETURN
690 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA7(J,K)=LA(J,K) @ Q7(J,K).
)=QQ(J,K) @ QQ(J,K)=0
700 IF LA7(J,K)=0 THEN ATR7(J,K)=999999 ELSE ATR7(J,K)=Q7(J,K)/LA7(J,K)
710 NEXT K @ NEXT J @ RETURN
720 LA=LA7(J,K) @ QQ=Q7(J,K) @ ATR=ATR7(J,K) @ RETURN
730 FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ LA8(J,K)=LA(J,K) @ Q8(J,K).
)=QQ(J,K) @ QQ(J,K)=0
```

```
740 IF LA8(J,K)=0 ;THEN ATR8(J,K)=999993 ELSE ATR8(J,K)=Q8(J,K)/LA8(J,K)
750 NEXT K ; NEXT J ; RETURN
760 LA=LA8(J,K) ; Q0=Q8(J,K) ; ATR=ATR8(J,K) ; RETURN
770 FOR J=1 TO DV(I) ; FOR K=1 TO SR(I,J) ; Q8(J,K)=LA(J,K) ; LA(J,K)=0 ; QS(I,J).
)=Q0(J,K) ; QU(J,K)=0 ; NEXT K ; NEXT J ; RETURN
780 IF LA9(J,K)=0 THEN ATR9(J,K)=999999 ELSE ATR9(J,K)=Q9(J,K)/LA9(J,K)
790 NEXT K ; NEXT J ; RETURN
800 LA=LA9(J,K) ; Q0=Q9(J,K) ; ATR=ATR9(J,K) ; RETURN
810 CLEAR ; FOR I=1 TO HY ; FOR J=1 TO DV(I)
820 DISP "PROPAGATION DISTANCE BETWEEN PORT ";I;" AND DEVICE ";J;" IN MICROSECO
S";@ INPUT D(I,J)
830 NEXT J ; NEXT I
840 CLEAR ; FOR I=1 TO HY ; DISP "WAIT TIME OF PORT ";I;" BEFORE TRANSMISSION RE
UEST (IN EVENT OF A COLLISION)";@ INPUT W(I)
850 NEXT I
860 CLEAR ; DISP "CHANNEL SETUP AND RELEASE TIME ASSIGNED THE VALUE 25 MICROSECO
DS."
870 QS=".000025" ; DISP " " ; DISP "PRESS <END LINE> OR ENTER THE PROPER VALUE "
; INPUT QS% IF QS <> "" THEN TSR=VAL (QS) ELSE TSR=.000025
880 DISP " " ; DISP "CHANNEL DATA TRANSFER RATE IS 6.25MBS" ; DISP " "
890 QS="6250000" ; DISP "PRESS <END LINE> OR ENTER THE PROPER VALUE ";@ INPUT QS%
IF QS <> "" THEN CR=VAL (QS) ELSE CR=6250000
900 CLEAR ; FOR I=1 TO HY ; FOR J=1 TO DV(I)
910 DISP "RATE AT WHICH DATA IS TRANSFERED FROM DEVICE ";J;" TO PORT ";I;
920 INPUT R(I,J)
930 LT(I,J)=1/R(I,J)
940 NEXT J ; NEXT I
950 GOSUB 960 ; GOTO 1080
960 FOR I=1 TO HY ; FOR J=1 TO DV(I) ; FOR K=1 TO SR(I,J)
970 ON I GOSUB 990,1000,1010,1020,1030,1040,1050,1060,1070
980 NEXT K ; NEXT J ; NEXT I ; RETURN
990 MNEG1(J,K)=0 ; TNG1(J,K)=0 ; TN1(J,K)=0 ; COL1(J,K)=0 ; RETURN
1000 MNEG2(J,K)=0 ; TNG2(J,K)=0 ; TN2(J,K)=0 ; COL2(J,K)=0 ; RETURN
1010 MNEG3(J,K)=0 ; TNG3(J,K)=0 ; TN3(J,K)=0 ; COL3(J,K)=0 ; RETURN
1020 MNEG4(J,K)=0 ; TNG4(J,K)=0 ; TN4(J,K)=0 ; COL4(J,K)=0 ; RETURN
1030 MNEG5(J,K)=0 ; TNG5(J,K)=0 ; TN5(J,K)=0 ; COL5(J,K)=0 ; RETURN
1040 MNEG6(J,K)=0 ; TNG6(J,K)=0 ; TN6(J,K)=0 ; COL6(J,K)=0 ; RETURN
1050 MNEG7(J,K)=0 ; TNG7(J,K)=0 ; TN7(J,K)=0 ; COL7(J,K)=0 ; RETURN
1060 MNEG8(J,K)=0 ; TNG8(J,K)=0 ; TN8(J,K)=0 ; COL8(J,K)=0 ; RETURN
1070 MNEG9(J,K)=0 ; TNG9(J,K)=0 ; TN9(J,K)=0 ; COL9(J,K)=0 ; RETURN
1080 NUMPROB=0
1090 PDS(0)=0 ; PRO(0)=0 ; FOR I=1 TO 200 ; CLEAR ; DISP "PREVIOUS COMBINATION "
;PDS(I-1);" PROBABILITY ";PRO(I-1) ; DISP " "
1100 DISP "SELECT (PORT,DEVICE,SOURCE) WHICH TRANSMITS TO (PORT,DEVICE,SOURCE) "
```

```
1110 DISP "FORMAT <PDSPDS>. THESE COMBINATIONS MUST BE ENTERED IN ORDER."
1120 DISP "ENTER <0> IF FINISHED ENTERING PROBABILITIES ";@ INPUT PDS(I)@ TIMES(
     I)=0
1130 IF PDS(I)=0 THEN 1260 ELSE NUMPROB=NUMPROB+1
1140 @ISP " ";@ DISP "PROBABILITY OF OCCURRENCE ";@ INPUT PRO(I)
1150 GOSUB 1160 @ GOTO 1250
1160 J=INT (PDS(I)/100000) @ K=INT (PDS(I)/10000)-J*10
1170 L=-(J*100)-K*10+INT (PDS(I)/1000) @ M=-(J*1000)-K*100-L*10+INT (PDS(I)/100)

1180 N=-(J*10000)-K*1000-L*100-M*10+INT (PDS(I)/10)
1190 O=-(J*100000)-K*10000-L*1000-M*100-N*10+PDS(I)
1200 A=J @ J=K @ K=L @ L @ ON A GOSUB 480,520,560,600,640,680,720,760,800
1210 CP1=QQ*LT(A,J)
1220 CP2=QQ*LT(M,N)
1230 IF CP1>CP2 THEN TL=CP1 ELSE TL=CP2
1240 T(I)=TSR+2000/CR+TL @ RETURN
1250 NEXT I @ PREJ=99 @ PREK=99
1260 SNUM=0 @ PREJ=99 @ PREK=99 @ CLEAR @ FOR I=1 TO 200 @ CLEAR @ DISP "ENTER I
     IJ-LM COMBINATIONS WHICH HAVE SOURCE DATA FILE DUMPS."
1270 DISP "ENTER A <0> WHEN COMPLETED." @ DISP " " @ DISP "SOURCE TO DESTINATION
     ";@ INPUT DIFL(I)@ IF DTFL(I)=0 THEN 1330
1280 WT(I)=0 @ SNUM=SNUM+1 @ J=INT (DIFL(I)/1000) @ K=DTFL(I)-J*1000 @ K=INT (K/
     10)
1290 IF J=PREJ AND K=PREK THEN BYTES(I)=BYTES(I-1) @ TIM(I)=TIM(I-1) @ GOTO 1320

1300 PREJ=J @ PREK=K @ DISP "# OF BYTES TO BE DUMPED ";@ INPUT BYTES(I)
1310 DISP "TIME INTERVAL BETWEEN DUMPS (IN SECONDS)";@ INPUT TIM(I)
1320 NEXT I
1330 IF AN=2 THEN 1720
1334 ! ****************************************************
1335 ! READ OR WRITE DATA TO THE DATA FILE (GETDATA = 999 -READ OR 888 -WRITE)
1336 ! LINES 1340-1710
1337 ! ****************************************************
1340 CLEAR @ CREATE DFNAMES.,2123.8
1350 DFNMS=DFNAMES$":D700" @ ASSIGN# 1 TO DFNMS
1360 IF GETDATA=999 THEN READ# 1,1 : HY ELSE PRINT# 1,1 : HY
1370 II=1 @ FOR J=1 TO HY @ II=II+1
1380 IF GETDATA=999 THEN READ# 1,II : DV(J) ELSE PRINT# 1,II : DV(J)
1390 NEXT J @ FOR I=1 TO HY @ FOR J=1 TO DV(I)
1400 II=II+1 @ IF GETDATA=999 THEN READ# 1,II : SR(I,J) ELSE PRINT# 1,II : SR(I,
     J)
1410 NEXT J @ NEXT I
1420 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
1430 IF GETDATA=888 THEN ON I GOSUB 480,520,560,600,640,680,720,760,800
```

```
1440 II=II+1
1450 IF GETDATA=999 THEN READ# 1,II : DV(J,K) ELSE PRINT# 1,II : DV
1460 II=II+1
1470 IF GETDATA=999 THEN READ# 1,II : LA(J,K) ELSE PRINT# 1,II : LA
1480 NEXT K $ NEXT J $ IF GETDATA=999 THEN ON I GOSUB 450,490,530,570,610,650,65
     ,730,770
1490 NEXT I
1500 FOR I=1 TO HY $ FOR J=1 TO DV(I) $ II=II+1
1510 IF GETDATA=999 THEN READ# 1,II : D(I,J) ELSE PRINT# 1,II : D(I,J)
1520 NEXT J $ NEXT I
1530 FOR I=1 TO HY $ II=II+1 $ IF GETDATA=999 THEN READ# 1,II : W(I) ELSE PRINT# 1,II : W(I)
     1,II ; W(I)
1540 NEXT I
1550 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : ISR ELSE PRINT# 1,II : ISR
1560 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : OR ELSE PRINT# 1,II : OR
1570 FOR I=1 TO HY $ FOR J=1 TO DV(I) $ II=II+1
1580 IF GETDATA=999 THEN READ# 1,II : R(I,J) $ LT(I,J)=1/R(I,J) ELSE PRINT# 1,II :
     R(I,J)
1590 NEXT J $ NEXT I
1600 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : NUMPROB ELSE PRINT# 1,II : NUMPR

1610 FOR I=1 TO NUMPROB $ II=II+1 $ IF GETDATA=999 THEN READ# 1,II : PDS(I) ELSE
     PRINT# 1,II : PDS(I)
1620 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : PRO(I) ELSE PRINT# 1,II : PRO(I)

1630 IF GETDATA=999 THEN TIMEST(I)=0 $ GOSUB 1160
1640 NEXT I
1650 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : SNUM ELSE PRINT# 1,II : SNUM
1660 FOR I=1 TO SNUM $ WT(I)=0 $ II=II+1 $ IF GETDATA=999 THEN READ# 1,II : DTFL
     (I) ELSE PRINT# 1,II : DTFL(I)
1670 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : BYTES(I) ELSE PRINT# 1,II : BYTE
     S(I)
1680 II=II+1 $ IF GETDATA=999 THEN READ# 1,II : TIM(I) ELSE PRINT# 1,II : TIM(I)

1690 NEXT I
1700 ASSIGN# 1 TO *
1710 GOSUB 960
1720 CLEAR $ DISP TAB (20);"MENU" $ DISP " " $ DISP "1    -- PRINT OUT CURRENT DA
     TA" $ DISP "2 -- CORRECT DATA ERRORS."
1730 DISP "3 -- RUN PROGRAM " $ DISP " " $ DISP "ENTER YOUR SELECTION ";$ INPU
     T SELECT
1740 IF SELECT<1 OR SELECT>3 THEN 1720
1750 IF SELECT=3 THEN 1760 ELSE ON SELECT GOTO 3840,4210
1760 SAVEAIR=99999 $ SAVELA=0
1770 FOR I=1 TO HY $ FOR J=1 TO DV(I) $ FOR K=1 TO SR(I,J)
1780 ON I GOSUB 480,520,560,600,640,680,720,760,800
```

```
1790 IF LA>SAVELA THEN SAVELA=LA @ SAVEIJK=I*100+J*10+K
1800 IF ATR=0 THEN 1820
1810 IF ATR<SAVEATR THEN SAVEATR=ATR @ SAVEATRIJK=I*100+J*10+K
1820 IF ATR=999999 THEN TLST=999999 ELSE TLST=0
1830 ON I GOSUB 1850,1860,1870,1880,1890,1900,1910,1920,1930
1840 NEXT K @ NEXT J @ NEXT I @ GOTO 1940
1850 TLST1(J,K)=TLST @ RETURN
1860 TLST2(J,K)=TLST @ RETURN
1870 TLST3(J,K)=TLST @ RETURN
1880 TLST4(J,K)=TLST @ RETURN
1890 TLST5(J,K)=TLST @ RETURN
1900 TLST6(J,K)=TLST @ RETURN
1910 TLST7(J,K)=TLST @ RETURN
1920 TLST8(J,K)=TLST @ RETURN
1930 TLST9(J,K)=TLST @ RETURN
1940 PRINT " " @ PRINT "FIRST USER IS ";SAVEIJK @ ITERNUM=0 @ NUMDEST=0
1950 PRINT " " @ PRINT "TOTAL TIME GONE BY ";SAVEATR @ CN=0 @ TIGB=SAVEATR
1960 CLEAR @ DISP "                         PRINTER MENU" @ DISP " " @ DISP "1 -- NO PRIN
OUT GIVEN ON EACH CYCLE"
1970 DISP "2 -- PRINTOUT GIVEN ON EACH CYCLE" @ DISP " " @ DISP "3 -- SPECIFY THE LAST
CYCLES TO BE PRINTED" @ DISP " "
1980 INPUT PR @ IF PR<1 OR PR>3 THEN CLEAR @ GOTO 1960
1990 IF PR=2 THEN PRINTER IS 701 ELSE PRINTER IS 1
2000 IF PR=3 THEN DISP "ENTER THE LAST X CYCLES WHICH ARE TO BE PRINTED ";@ INPU
NUMCYCLES
2005 ! ****************************************************************
2006 ! GENERATE A RANDOM NUMBER. THEN USE IT TO SELECT THE DESTINATION DEVICE
2007 ! LINES 2010-2140
2008 ! ****************************************************************
2010 XXX=RND
2020 IF PR=3 THEN 2030 ELSE 2040
2030 IF ITERNUM>= NUMITER-NUMCYCLES THEN PRINTER IS 701
2040 PRINT " " @ PRINT " " @ PRINT "ITERATION NUMBER ";ITERNUM+1 @ PRINT " " "
2050 FOR I=1 TO NUMPROB
2060 IJK=INT (PDS(I)/1000)
2070 IF IJK=SAVEIJK THEN NUMDEST=NUMDEST+1 @ SAVEEND=I ELSE 2090
2080 IF NUMDEST=1 THEN START=I @ PROB=PRO(I) @ PRINT "PROBABILITY ";PROB
2090 NEXT I @ PRINT "RANDOM NUMBER ";XXX
2100 IF XXX<PROB THEN SOURCE=START @ GOTO 2140
2110 FOR I=START TO SAVEEND
2120 IF XXX<= PROB THEN SOURCE=I @ GOTO 2140
2130 PROB=PROB+PRO(I+1) @ PRINT "PROBABILITY ";PROB @ NEXT I
2140 PRINT " " @ PRINT "DESTINATION ";PDS(SOURCE)-SAVEIJK*1000
2150 PRINT " " @ PRINT "PORT,DEVICE,SOURCE                    TOTAL TIME GONE BY SINCE LAST
TRANSMISSION" @ TIGBSLT=SAVEATR
```

64

```
2160 TIMESTT(SOURCE)=TIMESTT(SOURCE)+1
2170 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
2180 TLST=999999 @ ON I GOSUB 2210,2220,2230,2240,2250,2260,2270,2280,2290
2190 PRINT I;" ";J;" ";K;TAB (30);TLST
2200 NEXT K @ NEXT J @ NEXT I @ GOTO 2300
2210 IF TLST1(J,K)=999999 THEN RETURN ELSE TLST1(J,K)=TLST1(J,K)+TTGBSLT @ TLST=
TLST1(J,K) @ RETURN
2220 IF TLST2(J,K)=999999 THEN RETURN ELSE TLST2(J,K)=TLST2(J,K)+TTGBSLT @ TLST=
TLST2(J,K) @ RETURN
2230 IF TLST3(J,K)=999999 THEN RETURN ELSE TLST3(J,K)=TLST3(J,K)+TTGBSLT @ TLST=
TLST3(J,K) @ RETURN
2240 IF TLST4(J,K)=999999 THEN RETURN ELSE TLST4(J,K)=TLST4(J,K)+TTGBSLT @ TLST=
TLST4(J,K) @ RETURN
2250 IF TLST5(J,K)=999999 THEN RETURN ELSE TLST5(J,K)=TLST5(J,K)+TTGBSLT @ TLST=
TLST5(J,K) @ RETURN
2260 IF TLST6(J,K)=999999 THEN RETURN ELSE TLST6(J,K)=TLST6(J,K)+TTGBSLT @ TLST=
TLST6(J,K) @ RETURN
2270 IF TLST7(J,K)=999999 THEN RETURN ELSE TLST7(J,K)=TLST7(J,K)+TTGBSLT @ TLST=
TLST7(J,K) @ RETURN
2280 IF TLST8(J,K)=999999 THEN RETURN ELSE TLST8(J,K)=TLST8(J,K)+TTGBSLT @ TLST=
TLST8(J,K) @ RETURN
2290 IF TLST9(J,K)=999999 THEN RETURN ELSE TLST9(J,K)=TLST9(J,K)+TTGBSLT @ TLST=
TLST9(J,K) @ RETURN
2300 GOSUB 2310 @ GOTO 3020
2305 ! ****************************************************************
2306 ! FIND SMALL & SMALL2 TO BE USED TO CHECK FOR COLLISIONS AND NRTT
2307 ! LINES 2310-2540
2308 ! ****************************************************************
2310 PRINT " " @ PRINT "PORT,DEVICE,SOURCE          REMAINING TIME TO TRANSMIT (NO
RMALIZED FASHION)"
2320 SMALL=999988 @ SAVESM=999988 @ SMALL2=999988 @ SAVESM2=999988
2330 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
2340 ON I GOSUB 480,520,560,600,640,680,720,760,800
2350 ON I GOSUB 2370,2380,2390,2400,2410,2420,2430,2440,2450
2360 GOTO 2460
2370 TLST=TLST1(J,K)   @ RETURN
2380 TLST=TLST2(J,K)   @ RETURN
2390 TLST=TLST3(J,K)   @ RETURN
2400 TLST=TLST4(J,K)   @ RETURN
2410 TLST=TLST5(J,K)   @ RETURN
2420 TLST=TLST6(J,K)   @ RETURN
2430 TLST=TLST7(J,K)   @ RETURN
2440 TLST=TLST8(J,K)   @ RETURN
2450 TLST=TLST9(J,K)   @ RETURN
```

```
2460 IF ATR=999999 THEN NRTT=999999 ELSE NRTT=ATR-TLST
2470 IF CLSN$="Y" THEN SUB=-1 ELSE SUB=1
2480 ON I GOSUB 2550,2600,2650,2700,2750,2800,2850,2900,2950
2490 IF CLSN$="Y" THEN 2510
2500 PRINT I;" ";J;" ";K;TAB(30);NRTT
2510 IF NRTT<SMALL THEN CH1=SMALL @ SMALL=NRTT @ CH2=SAVESM @ SAVESM=I*100+J*10+
@ EQ$="Y"
2520 IF CH1<SMALL2 THEN SMALL2=CH1 @ SAVESM2=CH2
2530 IF NRTT=SMALL AND NRTT<SMALL2 AND EQ$="N" THEN SMALL2=NRTT @ SAVESM2=I*100+
*10+K
2540 EQ$="N" @ NEXT K @ NEXT J @ NEXT I @ EQ$="N" @ RETURN
2550 NRTT1(J,K)=NRTT @ IF NRTT<0 THEN TNG1(J,K)=TNG1(J,K)+NRTT @ TN1(J,K)=TN1(J,
)+SUB
2560 IF CLSN$ <> "Y" THEN 2580
2570 IF NRTT<0 THEN TNG1(J,K)=TNG1(J,K)-2*NRTT
2580 IF NRTT<MNEG1(J,K) THEN MNEG1(J,K)=NRTT
2590 RETURN
2600 NRTT2(J,K)=NRTT @ IF NRTT<0 THEN TNG2(J,K)=TNG2(J,K)+NRTT @ TN2(J,K)=TN2(J,
)+SUB
2610 IF NRTT<MNEG2(J,K) THEN MNEG2(J,K)=NRTT
2620 IF CLSN$ <> "Y" THEN 2640
2630 IF NRTT<0 THEN TNG2(J,K)=TNG2(J,K)-2*NRTT
2640 IF NRTT<MNEG1(J,K) THEN MNEG1(J,K)=NRTT
2650 NRTT3(J,K)=NRTT @ IF NRTT<0 THEN TNG3(J,K)=TNG3(J,K)+NRTT @ TN3(J,K)=TN3(J,
)+SUB
2660 IF CLSN$ <> "Y" THEN 2680
2670 IF NRTT<0 THEN TNG3(J,K)=TNG3(J,K)-2*NRTT
2680 IF NRTT<MNEG3(J,K) THEN MNEG3(J,K)=NRTT
2690 RETURN
2700 NRTT4(J,K)=NRTT @ IF NRTT<0 THEN TNG4(J,K)=TNG4(J,K)+NRTT @ TN4(J,K)=TN4(J,
)+SUB
2710 IF CLSN$ <> "Y" THEN 2730
2720 IF NRTT<0 THEN TNG4(J,K)=TNG4(J,K)-2*NRTT
2730 IF NRTT<MNEG4(J,K) THEN MNEG4(J,K)=NRTT
2740 RETURN
2750 NRTT5(J,K)=NRTT @ IF NRTT<0 THEN TNG5(J,K)=TNG5(J,K)+NRTT @ TN5(J,K)=TN5(J,
)+SUB
2760 IF CLSN$ <> "Y" THEN 2780
2770 IF NRTT<0 THEN TNG5(J,K)=TNG5(J,K)-2*NRTT
2780 IF NRTT<MNEG5(J,K) THEN MNEG5(J,K)=NRTT
2790 RETURN
2800 NRTT6(J,K)=NRTT @ IF NRTT<0 THEN TNG6(J,K)=TNG6(J,K)+NRTT @ TN6(J,K)=TN6(J,
K)+SUB
2810 IF CLSN$ <> "Y" THEN 2830
```

```
2820 IF NRTT<0 THEN TNG6(J,K)=TNG6(J,K)-2*NRTT
2830 IF NRTT<MNEG6(J,K) THEN MNEG6(J,K)=NRTT
2840 RETURN
2850 NRTT7(J,K)=NRTT @ IF NRTT<0 THEN TNG7(J,K)=TNG7(J,K)+NRTT @ TN7(J,K)=TN7(J,
)+SUB
2860 IF NRTT<MNEG7(J,K) THEN MNEG7(J,K)=NRTT
2870 IF CLSN$ <> "Y" THEN 2890
2880 IF NRTT<0 THEN TNG7(J,K)=TNG7(J,K)-2*NRTT
2890 RETURN
2900 NRTT8(J,K)=NRTT @ IF NRTT<0 THEN TNG8(J,K)=TNG8(J,K)+NRTT @ TN8(J,
)+SUB
2910 IF NRTT<MNEG8(J,K) THEN MNEG8(J,K)=NRTT
2920 IF CLSN$ <> "Y" THEN 2940
2930 IF NRTT<0 THEN TNG8(J,K)=TNG8(J,K)-2*NRTT
2940 RETURN
2950 NRTT9(J,K)=NRTT @ IF NRTT<0 THEN TNG9(J,K)=TNG9(J,K)+NRTT @ TN9(J,
)+SUB
2960 IF NRTT<MNEG9(J,K) THEN MNEG9(J,K)=NRTT
2970 IF CLSN$ <> "Y" THEN 2990
2980 IF NRTT<0 THEN TNG9(J,K)=TNG9(J,K)-2*NRTT
2990 RETURN
3005 ! **********************************************************
3006 ! THE COLLISION ALGORITHM.
3007 ! LINES 3020 - 3300
3008 ! **********************************************************
3020 AF$="F" @ IF INT ((PDS(SOURCE)-SAVESM*1000)/100)=INT (SAVESM/100) THEN AF$=
[" @ PRINTER IS 701
3021 IF AF$="T" THEN PRINT "TRANSMISSION ON SAME A400 SOURCE/DEST = ";PDS(SOURCE
@ CLNS="N" @ CLN$="Y"
3022 IF CLN$="Y" THEN 3090
3025 IF ABS (SMALL-SMALL2)<=.001 THEN PRINTER IS 701 ELSE GOTO 3260
3040 PRINT "A COLLISION OCCURRED BETWEEN ";SAVESM;" AND ";SAVESM2
3050 I=INT (SAVESM/100) @ L=INT (SAVESM2/100)
3060 IF W(I)<= W(L) THEN 3090
3070 SAVEIJK=SAVESM2 @ NUMDEST=0 @ SAVEATR=W(L) @ T(BG=TTGB+W(L) @ TIMESTT(SOURC
=TIMESTT(SOURCE)-1 @ CLN$="Y"
3080 PROB=0 @ CLNS="Y" @ GOSUB 2320 @ CLNS="N" @ GOTO 2010
3090 CN=CN+1 @ PRINT "COLLISION NUMBER ";CN
3100 I=INT (SAVESM/100) @ J=INT (SAVESM/10)-I*10 @ K=SAVESM-I*100-J*10
3110 ON I GOSUB 3150,3160,3170,3180,3190,3200,3210,3220,3230
3120 I=INT (SAVESM2/100) @ J=INT (SAVESM2/10)-I*10 @ K=SAVESM2-I*100-J*10
3130 ON I GOSUB 3150,3160,3170,3180,3190,3200,3210,3220,3230
3140 GOTO 3240
```

```
3150 COL1(J,K)=COL1(J,K)+1 @ RETURN
3160 COL2(J,K)=COL2(J,K)+1 @ RETURN
3170 COL3(J,K)=COL3(J,K)+1 @ RETURN
3180 COL4(J,K)=COL4(J,K)+1 @ RETURN
3190 COL5(J,K)=COL5(J,K)+1 @ RETURN
3200 COL6(J,K)=COL6(J,K)+1 @ RETURN
3210 COL7(J,K)=COL7(J,K)+1 @ RETURN
3220 COL8(J,K)=COL8(J,K)+1 @ RETURN
3230 COL9(J,K)=COL9(J,K)+1 @ RETURN
3240 IF CLN$="Y" THEN DT(SOURCE)=T(SOURCE) @ CLN$="N" ELSE DT(SOURCE)=T(SOURCE)+
(I) @ CLN$="N"
3250 GOTO 3300
3260 DT(SOURCE)=T(SOURCE)
3270 PRINT "NO COLLISION OCCURED " @ IF PR=1 THEN PRINTER IS 1
3280 IF PR=3 THEN 3290 ELSE 3300
3290 IF ITERNUM>=NUMITER-NUMCYCLES THEN 3300 ELSE PRINTER IS 1
3300 PRINT "DATA TRANSFER ";DT(SOURCE) @ IF AF$="T" THEN AF$="F" @ GOTO 3320
3310 BBT=BBT+DT(SOURCE)
3320 PRINT " " @ PRINT "PORT,DEVICE,SOURCE      ACCUMULATED WAITING TIMES SINCE
THE LAST TRANSMISSION"
3330 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
3340 IF I*100+J*10+K=SAVEIJK THEN TLST=0 ELSE GOTO 3370
3350 ON I GOSUB 1850,1860,1870,1880,1890,1900,1910,1920,1930
3360 GOTO 3390
3370 TTGBSLT=DT(SOURCE) @ TLST=999999
3380 ON I GOSUB 2210,2220,2230,2240,2250,2260,2270,2280,2290
3390 PRINT I;"  ";J;"  ";K;TAB (30);TLST
3400 NEXT K @ NEXT J @ NEXT I
3410 TTGB=TTGB+DT(SOURCE)
3420 PRINT "DATA TRANSFER COMPLETED: TOTAL TIME GONE BY ";TTGB
3430 GOSUB 2310
3440 PRINT "NEXT TRANSMISSION REQUEST BY ";SAVESM @ SAVEIJK=SAVESM
3450 TTNR=SMALL
3460 IF TTNR<0 THEN 3480
3470 TTGB=TTGB+TTNR
3480 TTGBSLT=TTNR @ SAVESM2=0 @ SAVESM=0 @ SMALL=0 @ SMALL2=0
3481 ! PRINT OUT CURRENT ENTRY DATA - EITHER FROM FILE OR USER ENTERED
3490 PRINT "TOTAL TIME THAT WILL BE GONE BY WHEN ";SAVESM;" STARTS TO TRANSMIT "
;TTGB
3500 NUMDEST=0 @ PROB=0 @ SAVEATR=TTNR @ SAVESM=0
3505 ! ********************************************************************
3506 ! SOURCE DUMP ALGORITHM   LINES 3510 - 3590
3507 ! ********************************************************************
```

```
3510 FOR H=1 TO SNUM @ IF TIM(H)<= TTGB-WT(H) THEN 3520 ELSE 3590
3520 WT(H)=TTGB @ J=INT (DTFL(H)/1000) @ K=INT ((DTFL(H)-J*1000)/100) @ L=INT ((
TFL(H)-J*1000-K*100)/10) @ M=DTFL(H)-J*1000-K*100-L*10
3530 CP1=BYTES(H)*LT(J,K) @ CP2=BYTES(H)*LT(L,M)
3535 PRINTER IS 701 @ PRINT "" @ PRINT "SOURCE ";J;" ";K;" DUMPED TO DESTINA
ION ";L;" ";M;" ";BYTES(H);" BYTES OF DATA"
3536 PRINT "TOTAL TIME GONE BY (BEFORE THE DUMP) ";TTGB
3540 IF CP1>CP2 THEN TL=CP1 ELSE TL=CP2
3550 TRANS=TSR+2000/CR+TL @ TTGB=TTGB+TRANS @ BBT=BBT+TRANS @ TGBSLT=TRANS
3555 PRINT "TOTAL TIME GONE BY (AFTER THE DUMP) ";TTGB @ PRINT "" @ IF PR=1 THE
PRINTER IS 1
556 IF PR=3 THEN 3557 ELSE 3560
557 IF ITERNUM>= NUMITER-NUMCYCLES THEN 3560 ELSE PRINTER IS 1
560 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
570 ON I GOSUB 2210,2220,2230,2240,2250,2260,2270,2280,2290
580 NEXT K @ NEXT J @ NEXT I
590 NEXT H @ TTGBSLT=TTNR
600 IF ITERNUM=NUMITER-1 THEN 3610 ELSE ITERNUM=ITERNUM+1 @ GOTO 2010
610 PRINTER IS 701
615 ! **********************************************************************
616 ! THE FINAL PRINTOUT GIVING A SUMMARY OF THE RUN
617 ! LINES 3620 - 3830
618 ! **********************************************************************
620 TOT=0 @ PRINT "" @ PRINT "SOURCE TO DESTINATION        # OF TIMES TRANSMIT
ED"
630 FOR I=1 TO NUMPROB @ PRINT PDS(I);TAB (30);TIMEST(I) @ TOT=TOT+TIMEST(I)
640 NEXT I
650 PRINT "TOTAL";TAB (30);TOT
660 PRINT "" @ PRINT "PORT,DEVICE,SOURCE     LONGEST WAITING TIME    AVG WAITIN
TIME    COLLISIONS"
570 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
580 ON I GOSUB 3720,3730,3740,3750,3760,3770,3780,3790,3800
590 IF TN=0 THEN AVG=0 ELSE AVG=TNEG/TN
700 PRINT I;" ";J;" ";K;TAB (25);MNEG;TAB (46);AVG;TAB (68);COLL
710 NEXT K @ NEXT J @ NEXT I @ GOTO 3810
720 MNEG=MNEG1(J,K) @ TNEG=TNG1(J,K) @ TN=TN1(J,K) @ COLL=COL1(J,K) @ RETURN
730 MNEG=MNEG2(J,K) @ TNEG=TNG2(J,K) @ TN=TN2(J,K) @ COLL=COL2(J,K) @ RETURN
740 MNEG=MNEG3(J,K) @ TNEG=TNG3(J,K) @ TN=TN3(J,K) @ COLL=COL3(J,K) @ RETURN
750 MNEG=MNEG4(J,K) @ TNEG=TNG4(J,K) @ TN=TN4(J,K) @ COLL=COL4(J,K) @ RETURN
760 MNEG=MNEG5(J,K) @ TNEG=TNG5(J,K) @ TN=TN5(J,K) @ COLL=COL5(J,K) @ RETURN
770 MNEG=MNEG6(J,K) @ TNEG=TNG6(J,K) @ TN=TN6(J,K) @ COLL=COL6(J,K) @ RETURN
780 MNEG=MNEG7(J,K) @ TNEG=TNG7(J,K) @ TN=TN7(J,K) @ COLL=COL7(J,K) @ RETURN
3790 MNEG=MNEG8(J,K) @ TNEG=TNG8(J,K) @ TN=TN8(J,K) @ COLL=COL8(J,K) @ RETURN
3800 MNEG=MNEG9(J,K) @ TNEG=TNG9(J,K) @ TN=TN9(J,K) @ COLL=COL9(J,K) @ RETURN
3810 PRINT "TOTAL TIME GONE BY = ";TTGB
```

```
4320 PRINT "BUS BUSY TIME = ";BBT
4330 END
4340 ! ***************************************************************
4345 ! PRINT OUT CURRENT DATA - EITHER FROM FILE OR ENTERED BY USER
4346 ! LINES 3850 - 4200
4347 ! ***************************************************************
4350 PRINTER IS 701
4360 PRINT "# OF HYPERCHANNEL PORTS = ";HY @ PRINT " "
4370 FOR I=1 TO HY @ PRINT "# OF DEVICES FOR PORT";I;" = ";DV(I) @ NEXT I @ I=1
     PRINT " "
4380 FOR K=1 TO DV(I)
4390 PRINT "# OF SOURCES FOR PORT ";I;" DEVICE ";K;" = ";SR(I,K)
4900 NEXT K @ I=I+1 @ IF I<= HY THEN 3880 ELSE I=0 @ PRINT " "
4910 PRINT "PORT,DEVICE,SOURCE           AVERAGE ARRIVAL RATE        # OF BYTES A/CU
     ULATED"
4320 I=I+1 @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
4330 ON I GOSUB 480,520,560,600,640,680,720,760,800
4340 PRINT I;" ";J;"     ";K;TAB (35);LA;TAB (60);QQ
4350 NEXT K @ NEXT J
4360 IF I=HY THEN 3970 ELSE GOTO 3920
4970 PRINT " " @ FOR I=1 TO HY @ FOR J=1 TO DV(I)
4980 PRINT "PROPAGATION DISTANCE BETWEEN PORT ";I;" AND DEVICE ";J;" = ";D(I,J)
4990 NEXT J @ NEXT I @ PRINT " "
5000 FOR I=1 TO HY
5010 PRINT "WAIT TIME OF PORT ";I;" BEFORE TRANSMISSION REQUEST (IN EVENT OF A C
     LLISION) ";W(I)
5020 NEXT I
5030 PRINT " " @ PRINT " " @ PRINT "CHANNEL SETUP AND RELEASE TIME = ";TSR @ PRI
     T " "
5040 PRINT "CHANNEL DATA TRANSFER RATE = ";CR
5050 PRINT " " @ PRINT "PORT,DEVICE          TRANSFER RATE          LOAD T
     MES "
5060 FOR I=1 TO HY @ FOR J=1 TO DV(I)
5070 PRINT I;"   ";J;TAB (30);R(I,J);TAB (54);LT(I,J)
5080 NEXT J @ NEXT I
5090 PRINT " " @ PRINT "COMBINATIONS (IJK - LMN)   PROBABILITY  TIME TO TRANSMIT
     (IJK) BYTES (IJK - LMN)"
5100 FOR I=1 TO NUMPROB
5110 PRINT PDS(I);TAB (30);PRO(I);TAB (40);T(I)
5120 NEXT I
5130 PRINT " " @ PRINT "PORT,DEVICE,SOURCE          AVERAGE TIME TO NEXT TRANSMISSIO
     REQUEST "
5140 FOR I=1 TO HY @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J)
5150 ON I GOSUB 480,520,560,600,640,680,720,760,800
```

```
4160 PRINT I;" ";J;" ";K:TAB (30);ATR
4170 NEXT K @ NEXT J @ NEXT I
4180 PRINT " " @ PRINT "IJ-LM DATA FILE DUMP     BYTES TO BE DUMPED    TIME BETWEE
     DUMPS (IN SECONDS)"
4190 FOR I=1 TO SNUM @ PRINT DIFL(I);TAB (30);BYTES(I);TAB (50);TIM(I)
4200 NEXT I @ GOTO 1720
4210 ! *************************************************************
4215 ! THE EDIT ROUTINE - SAVES CORRECTED DATA TO FILE
4216 ! LINES 4220 - 4950
4217 ! *************************************************************
4220 CLEAR @ DISP "         EDIT MENU" @ DISP " "
4230 DISP "1  --   AVERAGE ARRIVAL RATES"
4240 DISP "2  --   NUMBER OF BYTES ACCUMULATED"
4250 DISP "3  --   PROPAGATION DISTANCES"
4260 DISP "4  --   WAIT TIMES"
4270 DISP "5  --   CHANNEL SETUP AND RELEASE TIME"
4280 DISP "6  --   CHANNEL DATA TRANSFER RATE"
4290 DISP "7  --   TRANSFER RATES"
4300 DISP "8  --   PROBABILITY DATA"
4310 DISP "9  --   SOURCE DATA DUMPS"
4320 DISP "10 --   TERMINATE EDIT MODE"
4330 DISP " " @ DISP "ENTER YOUR SELECTION ";@ INPUT EDT
4340 IF EDT<1 OR EDT>10 THEN 4210
4350 ON EDT GOTO 4360,4450,4540,4590,4630,4660,4690,4760,4850,4950
4360 FOR I=1 TO HY @ CLEAR @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ CLEAR
4370 ON I GOSUB 480,520,560,600,640,680,720,760,800
4380 DISP "PORT ";I;" DEVICE ";J;" SOURCE ";K @ DISP @ DISP
4390 LA(J,K)=LA @ QQ(J,K)=QQ
4400 DISP "AVERAGE ARRIVAL RATE = ";LA
4410 QS=" " @ DISP " " @ DISP " " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR
     ITER THE CORRECT VALUE ";@ INPUT QS
4420 IF QS <> "" THEN LA(J,K)=VAL (QS)
4430 NEXT K @ NEXT J @ ON I GOSUB 450,490,530,570,610,650,690,730,770
4440 NEXT I @ GOTO 4210
4450 FOR I=1 TO HY @ CLEAR @ FOR J=1 TO DV(I) @ FOR K=1 TO SR(I,J) @ CLEAR
4460 ON I GOSUB 480,520,560,600,640,680,720,760,800
4470 DISP "PORT ";I;" DEVICE ";J;" SOURCE ";K @ DISP @ DISP
4480 QQ(J,K)=QQ @ LA(J,K)=LA
4490 DISP "NUMBER OF BYTES ACCUMULATED = ";QQ
4500 QS=" " @ DISP " " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR
     ITER THE CORRECT VALUE ";@ INPUT QS
4510 IF QS <> "" THEN QQ(J,K)=VAL (QS)
4520 NEXT K @ NEXT J @ ON I GOSUB 450,490,530,570,610,650,690,730,770
4530 NEXT I @ GOTO 4840
```

```
540 CLEAR @ FOR I=1 TO HY @ FOR J=1 TO DV(I) @ CLEAR
550 DISP "PROPAGATION DISTANCE BETWEEN PORT ";I;" AND DEVICE ";J;" IN MICROSECO
DS = ";D(I,J) @ QS="."
560 DISP " " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE CORRECT VA
UE ";@ INPUT QS
570 IF QS <> "" THEN D(I,J)=VAL (QS)
580 NEXT J @ NEXT I @ GOTO 4210
590 CLEAR @ FOR I=1 TO HY @ CLEAR @ DISP "WAIT TIME OF PORT ";I;" BEFORE TRANSM
SSION REQUEST = ";W(I)
600 DISP " " @ QS="." @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE C
RRECT VALUE ";@ INPUT QS
610 IF QS <> "" THEN W(I)=VAL (QS)
620 NEXT I @ GOTO 4210
630 CLEAR @ DISP "CHANNEL SETUP AND RELEASE TIME = ";TSR
640 QS="." @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE P
PER VALUE ";@ INPUT QS@ IF QS <> "" THEN TSR=VAL (QS)
650 GOTO 4840
660 CLEAR @ DISP "CHANNEL DATA TRANSFER RATE = ";CR @ DISP " "
670 QS="." @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENER THE PROPER VALUE
@ INPUT QS@ IF QS <> "" THEN CR=VAL (QS)
680 GOTO 4840
690 CLEAR @ FOR I=1 TO HY @ FOR J=1 TO DV(I) @ CLEAR
700 DISP "RATE AT WHICH DATA IS TRANSFERED FROM DEVICE ";J;" TO PORT ";I;" = ";
I,J)
'10 QS="." @ DISP " " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE C
RECT VALUE ";@ INPUT QS
20 IF QS <> "" THEN R(I,J)=VAL (QS)
30 LT(I,J)=1/R(I,J)
40 NEXT J @ NEXT I
50 GOTO 4840
60 CLEAR @ FOR I=1 TO NUMPROB
70 CLEAR @ DISP "(PORT,DEVICE,SOURCE) TRANSMITS TO (PORT,DEVICE,SOURCE) CODE
";PDS(I) @ DISP " "
80 QS="." @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE CORRECT VALL
";@ INPUT QS
90 IF QS <> "" THEN PDS(I)=VAL (QS)
00 DISP " " @ DISP "PROBABILITY = ";PRO(I) @ DISP " "
10 QS="." @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE CORRECT VALU
";@ INPUT QS
4820 IF QS <> "" THEN PRO(I)=VAL (QS)
```

```
1830 NEXT I
1840 FOR I=1 TO NUMPROB @ GOSUB 1160 @ NEXT I @ GOTO 4210
1850 CLEAR @ FOR I=1 TO SNUM @ CLEAR @ DISP "(IJ - LF) SOURCE DATA FILE DUMPS TO
     DESTINATION LM, CODE = ";DTFL(I) @ DISP " "
1860 QS=" " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE CORRECT VALU
     ";@ INPUT QS
1870 IF QS <> "" THEN DTFL(I)=VAL (QS)
1880 DISP " " @ DISP "# OF BYTES TO BE DUMPED ";BYTES(I) @ DISP " "
1890 QS=" " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE CORRECT VALU
     ";@ INPUT QS
1900 IF QS <> "" THEN BYTES(I)=VAL (QS)
1910 DISP " " @ DISP "TIME INTERVAL BETWEEN DUMPS ";TIM(I) @ DISP " "
1920 QS=" " @ DISP "PRESS ENTER TO RETAIN CURRENT DATA OR ENTER THE CORRECT VALU
     ";@ INPUT QS
1930 IF QS <> "" THEN TIM(I)=VAL (QS)
1940 NEXT I @ GOTO 4210
1950 GETDATA=888 @ ON AN GOTO 1350,1720,1350
```

APPENDIX II

PASCAL SIMULATIONS ALGORITHM PROGRAM

A listing of the PASCAL simulation algorithm program is presented in this appendix. The program contains comments, but is not considered to be user oriented at this point. This program is FORTRAN based, but requires software support for PASCAL in the host computer.

@ASG,A AUX-OUT.
FACILITY WARNING   10DDC0C00000

@ASG,A DESCRIP-FILE.
FACILITY WARNING   100000000000

@PAS,IS
Pascal (Ver.2.01LR, updated 09/24/81) - 07/01/83 16:39:06

74

```
     1                (*************************************************
     2                (*                                              *
     3                (*                                              *
     4                (*                                              *
     5                (*                                              *
     6                (*                                              *
     7                (*     TITLE:                                   *
     8                (*       Simulation of a HYPERchannel Network:  *
     9                (*       A Model of the Huntsville Operations Support Center *
    10                (*                                              *
    11                (*     AUTHOR:                                  *
    12                (*       John D. Mauldin                        *
    13                (*                                              *
    14                (*       Mississippi State University           *
    15                (*       May, 1983                              *
    16                (*                                              *
    17                (*                                              *
    18                (*     ABSTRACT:                                *
    19                (*                                              *
    20                (*                                              *
    21                (*                                              *
    22                (************************************************)

    23  program MOD1(INPUT,OUTPUT,TERMINAL,DESCRIP_FILE,AUX_OUT);

    24                (***********************************************)
    25                (***********************************************)
    26                (*                                             *)
    27                (*        D A T A   D E C L A R A T I O N S    *)
    28                (*                                             *)
    29                (***********************************************)
    30                (***********************************************)

    31  const
    32    MAX_NUM_SOURCES  = 3;
    33    MAX-NUM-ADAPTERS = 4;
    34    NUM_OF_ADAPTERS  = 4;
    35    LPP              = 86;
    36    TNUM_DEV         = 11;
    37    TRUNK_OVERHEAD   = 0.000025 ; (* Trunk set-up and release time *)
    38    TRUNK-RATE       = 50E6 ;     (* Trunk tx rate in bits/second *)
    39    ONE              = 1;
    40    ZERO             = 0;
    41    COLL_EPS         = 0.001;   (* Increment to determine collisions *)

    42  type
    43    SOURCE_DESCRIPTIONS = record
    44       TX_RATE : real ; (* Avg number of bytes/sec *)
    45    end;

    46    DEVICE_RECORD = record
    47       DEV_NUM      : boolean;   (* TRUE if device attached to port *)
    48                     : integer;   (* Device number *)
    49       BUFFER_SIZE  : integer;   (* Number of bits accumulated from a *)
    50                                  (* off-net source before the device requests *)
    51                                  (* a trunk transmission *)
    52       NUM_OF_SOURCES : integer;
    53       SOURCE       : array[1..MAX_NUM_SOURCES] of SOURCE_DESCRIPTIONS;
    54       TFER_RATE    : real;      (* I/O port transfer rate from dev to adapt in bytes/sec *)
    55       LOAD_TIME    : real;      (* inverse of TFER_RATE = time for dev to load adapt buffer *)
    56       NEXT_TX      : real;      (* time until next transmission *)
    57       LAST_TRUNK_TX : real;
    58       TX_INTRVL    : real;      (* time between tx requests based on *)
    59                                  (* aggregate source transj rates from offnet sources *)
    60       TX_CT        : integer;   (* Device transmission tally *)
    61       WAIT_CT      : integer;   (* Device waits tally *)
    62       COLL_CT      : integer;   (* Device collision tally *)
    63       RX_CT        : integer;   (* Device receiving tally *)
    64       TX_TIME      : real;      (* time device spent in transmissions *)
```

```
  WAIT_TIME        : real;        (* Time device spent in wait delays *)
  COLL_TIME        : real;        (* Time device spent in coll. waits *)
  RX_TIME          :: real;       (* Time device spent receiving trunk (x *)
  end;

ADAPTER_RECORDS = record
  DEVICE    : array[1..6] of DEVICE_RECORDS;
  PROP_DIST_TO :: array[1..NUM_OF_ADAPTERS] of real;  (* Number of seconds
                                   required to transmit from one adapter
                                   to each other adapter on the net *)
  PRIORITY_DELAY    : real;       (* Number of seconds of assigned wait time in
                                   event of wait during transmission *)
  END_DELAY       : real;         {* Wait time if wait flip flop enabled *)
  ATX_CT          :: integer;     (* Tally of adapter transmissions *)
  AWAIT_CT        :: integer;     (* Tally of adapter waits *)
  ACOLL_CT        :: integer;     (* Tally of adapter collisions *)
  ATX_TIME        :: real;        (* Time adapter spent transmitting *)
  AWAIT_TIME      : real;         (* Time adapter spent in wait delays *)
  ACOLL_TIME      : real;         (* Time adapter spent in collisions *)
  end;

TEXTFILE = file of CHAR;

MODE_TYPE = (INTERACTIVE, FILE_INPUT);

CLOCK_COND = (NORMAL,COLLISION,OTHER);

var
  ADAPTER   : array[1..NUM_OF_ADAPTERS] of ADAPTER_RECORDS;
  PR        : array[1..TNUM_DEV,1..TNUM_DEV] of real;   (* Probability
                                    of transmission matrix *)
  BITS,TX;
  TX,TALLY,TOTAL_ATTEMPTS,
  MAX_TX,
  WAIT_TALLY,
  COLLISION_TALLY,
  RETRY_TALLY,
  I,J,K,D_NUM      : integer;     (* Run time for prog in simulation secs *)
  MAX_TIME_TIME,                  (* System clock recording total elapsed time *)
  CURRENT_TIME,
  TIME_ACTIVE,
  LAST_TRUNK_TX    : real;        (* Time of last successful trunk transmission *)
  U,IU             : integer;     (* Seed for random number generator *)
  RESP             : packed array[1..80] of char;
  DESCRIP_FILE,AUX_OUT : TEXTFILE;
  INPUT_MODE       : MODE_TYPE;
  CONDITION        : array[CLOCK_COND] of CLOCK_COND;
  COND1            : CLOCK_COND;
  TMITTR_RCVR      : DEVICE_RECORD;
  PRINT_ALL        : boolean;
  LCT,PCT,JK       : integer;

(*******************************************)
(*                                         *)
(*     P R O C E D U R E    D E F I N I T I O N S  *)
(*                                         *)
(*******************************************)

function UNIFORM(ZERO,ONE:real; var U:INTEGER):real;
    extern;
    {* calculates a pseudorandom number in range *}
    {* 0<num<1.                                  *}

(*******************************************)
(*                                         *)
function TIME_TO_NEXT_TX(DEVICE: DEVICE_RECORD) :real;
    {* Calculates the remaining time until device
       requests a transmission.                *}
(*******************************************)
```

```
begin DEVICE do
with DEVICE do
TIME_TO_NEXT_TX:=(CURRENT_TIME - LAST_TRUNK_TX) - TX_INTRVL;
end;

(*********************************************)
(*                                           *)
(*  procedure PRINT_WAIT_STATS(TMTTR: DEVICE_RECORD);  *)
(*  Prints statistics on successful trunk tx.   *)
(*                                           *)
(*********************************************)

var
  W_ADAPT,
  W_DEV         : integer;

begin
  W_DEV:= TMTTR.DEV_NUM mod 10;
  W_ADAPT:= (TMTTR.DEV_NUM mod 100) div 10;

  writeln(OUTPUT);  (* WAIT CONDITION ENCOUNTERED **')
  writeln(OUTPUT,'     Time: ',current_time:12:7);
  writeln(OUTPUT,' Transmitter: adapter ',W_ADAPT:5);
  writeln('  ',':3,'               device  ',W_DEV:3);
  writeln('  ',:17,'               device  ',W_DEV:3);

end;  (* PRINT TX STATS *)

(*********************************************)
(*                                           *)
(*  procedure PRINT_TX_STATS(TMTTR,RCVR: DEVICE_RECORD);  *)
(*  Prints statistics on successful trunk tx.   *)
(*                                           *)
(*********************************************)

var
  T_ADAPT,R_ADAPT,
  T_DEV,R_DEV       : integer;

begin
  T_DEV:= TMTTR.DEV_NUM mod 10;
  T_ADAPT:= (TMTTR.DEV_NUM mod 100) div 10;

  R_DEV := RCVR.DEV_NUM mod 10;
  R_ADAPT:= (RCVR.DEV_NUM mod 100) div 10;

  writeln(OUTPUT);  (* SUCCESSFUL TRANSMISSION **')
  writeln(OUTPUT,'     Time: ',current_time:12:7);
  writeln('  ',:17,' Transmitter:  adapter  ',T_ADAPT:5);
  writeln('  ',:24,'              device  ',T_DEV:3);
  writeln('  ',:17,' Reciever  :  adapter  ',R_ADAPT:5);
  writeln('  ',:17,'              device  ',R_DEV:3);

end;  (* PRINT TX STATS *)

(*********************************************)
(*                                           *)
(*  procedure PRINT_COLLISION_STATS(TMTTR,RCVR: DEVICE_RECORD);  *)
(*  Prints stats on event of collision.        *)
(*                                           *)
(*********************************************)

var
  T_ADAPT,P_ADAPT,
  T_DEV,R_DEV       : integer;

begin
  T_DEV:= TMTTR.DEV_NUM mod 10;
  T_ADAPT:= (TMTTR.DEV_NUM mod 100) div 10;
```

```pascal
        R_DEV := RCVR.DEV_NUM mod 10;
        R_ADAPT:= (RCVR.DEV_NUM mod 100) div 10;

        writeln(OUTPUT);
        writeln(OUTPUT,'** UNSUCCESSFUL TRANSMISSION -- COLLISION OCCURRED **');
        writeln(OUTPUT,'    Time:',current_time:12:7);
        writeln('    Transmitter: adapter ',T_ADAPT:3);
        writeln('               device ',T_DEV:3);
        writeln('    Reciever  : adapter ',R_ADAPT:3);
        writeln('               device ',R_DEV:3);
      end;   (* PRINT COLLISION STATS *)

    {******************************************}
    {                                          }
    {       procedure NEWPAGE;                 }
    {       Spaces output page of AUX_OUT to top of new page. }
    {******************************************}

      begin
        PCT:=PCT+1;
        LCT:=LPP-LCT+1;
        for JK:=1 to LCT do
          writeln(AUX_OUT);
        LCT:=0;
        writeln(AUX_OUT,'       ':125,'page ',PCT:2);
        LCT:=LCT+1;
      end; (* procedure NEWPAGE *)

    {******************************************}
    {                                          }
    {  procedure PRINT_NETWORK_STATS;          }
    {  Prints cumulative statistics of network at end }
    {  of simulation.                          }
    {******************************************}

    var
      PER_CENT_ACTIVE  : real;

    begin
      NEWPAGE;
      PER_CENT_ACTIVE:=TIME_ACTIVE/CURRENT_TIME*100.0;
      writeln(AUX_OUT,'':40,' *** END OF RUN NETWORK STATISTICS ***');
      writeln(AUX_OUT);
      writeln(AUX_OUT,'':40,' Current time: ',CURRENT_TIME:12:4,' secs');
      writeln(AUX_OUT,'':40,' Successful transmissions: ',TX_TALLY:5);
      writeln(AUX_OUT,'':40,' Collisions  ',COLLISION_TALLY:5);
      writeln(AUX_OUT,'':40,' Waits       ',WAIT_TALLY:5);
      writeln(AUX_OUT,'':40,' Total attempts ',TOTAL_ATTEMPTS:5);
      writeln(AUX_OUT,'':40,' Total time active ',TIME_ACTIVE:10:7,' secs');
      writeln(AUX_OUT,'':40,' % Total time active ',PER_CENT_ACTIVE:8:2,' %');
      writeln(AUX_OUT,'':40,' Total Bytes transmitted : ',BITS_TX DIV 8:12);
      writeln(AUX_OUT,'':40,' Seed for RNG ',IU:7);
      LCT:=LCT+16;

      writeln(OUTPUT);writeln(OUTPUT);
      writeln(OUTPUT,' *** END OF RUN ***');
      writeln(OUTPUT,'    Current time: ',CURRENT_TIME:12:4,' secs');
      writeln(OUTPUT,'    Successful transmissions: ',TX_TALLY:5);
      writeln(OUTPUT,'    Collisions  ',COLLISION_TALLY:5);
      writeln(OUTPUT,'    Waits       ',WAIT_TALLY:5);
      writeln(OUTPUT,'    Total attempts ',TOTAL_ATTEMPTS:5);
      writeln(OUTPUT,'    Total time active ',TIME_ACTIVE:10:4,' secs');
      writeln(OUTPUT,'    % Total time active ',PER_CENT_ACTIVE:8:2,' %');
      writeln(OUTPUT,'    Total Bytes transmitted : ',BITS_TX DIV 8:12);
      writeln(OUTPUT,'    Seed for RNG ',IU:7);
```

78

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OF POOR QUALITY

```
        end;   (* PRINT NETWORK STATS *)

  (*******************************************************************)
  (*   function TRANSFER_TIME(SENDER,RECEIVER :                      *)
  (*                          DEVICE_RECORD): real;                  *)
  (*     Calculates time required to transmit a message             *)
  (*     from a sender to a receiver.                                *)
  (*     Trunk overhead time includes the fixed delay for each      *)
  (*     adapter which is length of time required by a sending      *)
  (*     device to receive a response from.                         *)
  (*******************************************************************)

        var
          T,SLOWER_RATE: real;
          PCKT_CT     : integer;

        begin

          SLOWER_RATE:= SENDER.TFER_RATE;
          if RECEIVER.TFER_RATE < SLOWER_RATE then
             SLOWER_RATE:= RECEIVER.TFER_RATE;

          PCKT_CT:= round(SENDER.BUFFER_SIZE/2048);

          case PCKT_CT of
            0:  T:=TRUNK_OVERHEAD;

            1:  T:= 2048/TRUNK_RATE + TRUNK_OVERHEAD;

            otherwise:  T:= 2048/SENDER.TFER_RATE + 2048/TRUNK_RATE +
                            ((PCKT_CT-2)*2048)/SLOWER_RATE + TRUNK_OVERHEAD
          end;

          TRANSFER_TIME:=T;

        end;

  (*****************************************************************)
  (*   procedure UPDATE_CLOCKS(COND:CLOCK_COND);                  *)
  (*     Updates both the system clocks and device                *)
  (*     clocks whenever a system action has                      *)
  (*     occurred.                                                 *)
  (*****************************************************************)

        var
          TA,TD,RA,RD: integer;
          DELAY_TIME: real;
          TIME,T1: real;

        begin  (* A is transmitter adapter no., D is devive no. *)

          TA:= (TMITTR.DEV_NUM mod 100) div 10;
          RA:= (RCVR.DEV_NOM mod 100) div 10;

          TD:= TMITTR.DEV_NUM mod 10;
          RD:= RCVR.DEV_NOM mod 10;

          case COND of
            NORPAL:  begin
                     TIME:= TRANSFER_TIME(TMITTR,RCVR);

                     BITS_TX:=BITS_TX+ TMITTR.BUFFER_SIZE;

                     (* Update system clock *)

                     CURRENT_TIME:= CURRENT_TIME+TIME;

                     (* Update each device clock *)
```

```
for I:= 1 to NUM_OF_ADAPTERS do
  for J:=1 to 4 do
    with ADAPTER[I].DEVICE[J] do
      if (not OPEN) and (NOT((I=1) and (ID=J))) then
        if NEXT_TX <= CURRENT_TIME then
          begin
            DELAY_TIME:=ADAPTER[I].PRIORITY_DELAY + ADAPTER[I].END_DELAY;
            NEXT_TX:=CURRENT_TIME + DELAY_TIME;
            WAIT_TALLY:= WAIT_TALLY + 1;
            WAIT_CT:=WAIT_CT+T;
            WAIT_TIME:=WAIT_TIME+DELAY_TIME+TIME;

            if PRINT_ALL then
              PRINT_WAIT_STATS(ADAPTER[I].DEVICE[J]);
          end; (* NEXT_TX <= 0 *)
      end;

      (* Reset transmitter clock *)
      with ADAPTER[TA].DEVICE[ID] do
      begin
        NEXT_TX:= CURRENT_TIME+ TX_INTRVL;
        LAST-TRUNK_TX:=CURRENT_TIME;
        TX_CT:=TX_CT + 1;
        TX_TIME :=TX_TIME + TIME
      end;-(* with ADAPTER[TA].DEVICE[TD] *)

      with ADAPTER[RA].DEVICE[RD] do
      begin
        RX_CT:=RX_CT + 1;
        RX_TIME:=RX_TIME+TIME;
      end; (* with ADAPTER[RA].DEVICE[RD] *)

      TIME_ACTIVE:=TIME_ACTIVE+TRANSFER_TIME(TMITTR,RCVR);

    end; (* NORMAL case *)

    COLLISION : begin
      with ADAPTER[TA].DEVICE[TD] do
      begin
        COLL_EPS := COLL_EPS + (UNIFORM(ZERO,ONE,U)/(1.0/COLL_EPS));
        NEXT_TX:=NEXT_TX+T1;
        COLL_CT:=COLL_CT+1;
        COLL_TIME:=COLL_TIME+ T
      end; (* with ADAPTER[TA].DEVICE[D] *)
    end; (* COLLISION case *)

    OTHER : begin

    end; (* OTHER case *)
  end; (* case *)
end; (* UPDATE CLOCKS *)

(*****************************************)
(* function TX_INTERVAL(DEVICE : DEVICE_RECORD) :real;
(* calculates the time interval between requests.
(* for trunk transmissions. Based on the amount
(* of data (rate) received by a device from an
(* off-net sources and the size of the device
(* buffer.
(*****************************************)

var
  I             : integer;
  AGGREGATE_RATE: real;
begin
  AGGREGATE_RATE := 0.00;
  for I := 1 to DEVICE.NUM_OF_SOURCES do
```

```
        begin
          AGGREGATE_RATE := AGGREGATE_RATE + DEVICE.SOURCE[I].TX_RATE
        end;

        if AGGREGATE_RATE <> 0.0 THEN
          TX_INTERVAL := DEVICE.BUFFER_SIZE/AGGREGATE_RATE
        else
          TX_INTERVAL := 1E7;

A     end;

      {***************************************************}
      {*                                                 *}
      {*    procedure FIND_NEXT(var TMITTER:DEVICE_RECORD);  *}
A     {*    Determines the next transmitter by examining *}
      {*    each device's time until next transmission.  *}
      {*    Next tmittr is device with shortest time until *}
      {*    next transmission.                           *}
      {***************************************************}

A     var
        I,J    : integer;

      begin

A       TMITTER.NEXT_TX:=1000.0;

        for I:=1 to NUM_OF_ADAPTERS do
          for J:=1 to 4 do
            with ADAPTER[I].DEVICE[J] do
              if not OPEN then
                if NEXT_TX < TMITTER.NEXT_TX then
A                 TMITTER:=ADAPTER[I].DEVICE[J];

      end;   (* FIND NEXT TRANSMITTER *)

A     {***************************************************}
      {*                                                 *}
      {*   procedure PICK_A(var RECEIVER:DEVICE_RECORD;SENDER:DEVICE_RECORD); *}
A     {*   Picks an eligible receiver for the current    *}
      {*   transmitter based on the normalized trnsmission *}
      {*   probability matrix.                           *}
      {***************************************************}

A     var
        I,J,K,L : integer;
        A,D     : boolean;
        FOUND   : boolean;
        PROB    : real;

A     begin

        PROB := UNIFORM(ZERO,ONE,U);

        I:= SENDER.DEV_NUM div 100;
A       J:=1;
        while (PR(I,J) < PROB) and (J < D_NUM) do
          J:=J+1;

          (* J is now receiver device number *)
          (* Find adapter and device num for dev num J *)

A         A:=1; K:=1;
          D:=1; L:=1;
          FOUND:=false;

          while (K<= NUM_OF_ADAPTERS) and (not FOUND) do
A           begin
              while (L<= 4 ) and (not FOUND) do
              begin
                with ADAPTER[K].DEVICE[L] do
                begin
```

```
                if not FOUND then
                    if DEV_NUM div 100 = J then
                        begin
                            FOUND:=true;
                            K:=K;
                            L:=L;  (* each ifs *)
                        end;
                    L:=L+1;  (* with *)
                end;  (* while L<=4 and not FOUND *)
                K:=K+1;
                L:=1;
            end;  (* while K<= num adapters and not FOUND *)

        RECEIVER:=ADAPTER[A].DEVICE[D];

    end;  (* PICK A RECEIVER *)

(***********************************************)
(*                                             *)
(*    function A_COLLISION : boolean;          *)
(*    determines the chance of a collision occurring *)
(*    for a given transmission attempt. Collision    *)
(*    occurs if two transmitters attempt to transmit *)
(*    within 0.01 seconds of each other.       *)
(*                                             *)
(***********************************************)

    var
        i,j : integer;

    begin

        A_COLLISION := false;

        for i:=1 to NUM_OF ADAPTERS do
            for j:=1 to 2 do
                with ADAPTER[i].DEVICE[j] do
                    if not OPEN then
                        if TMITTR.DEV_NUM <> DEV_NUM then
                            if abs(TMITTR.NEXT_TX-NEXT_TX) < COLL_EPS then
                                A_COLLISION:= true;

    end;  (* COLLISION DETECTION *)

(***********************************************)
(*                                             *)
(*    procedure ACTIVITY_SUMMARY;              *)
(*                                             *)
(***********************************************)

    var
        I,J     : integer;
        PC_WAIT_DEV,
        PC_ACT_TR,
        PC_TX_TR,
        PC_TX-DEV,
        PC_WAIT_TR,
        WAIT_PC-DEV,
        PC_COLL-TR,
        PC_COLL-DEV,
        DEV_ACTIVE_TIME  : real;

    begin

        writeln(AUX_OUT);
        writeln(AUX_OUT);
        writeln(AUX_OUT);
        writeln(AUX_OUT, ':45,'DEVICE ACTIVITY SUMMARIES');
        writeln(AUX_OUT, ':52,'(SECONDS)');
        writeln(AUX_OUT);
        write(AUX_OUT, ':3,'ADP DEV'):9,'TIME','':10);
        write(AUX_OUT, ':7,'TIME':7,'TIME');
        write(AUX_OUT,'TIME IN',':10,'TIME');
```

```
write(AUX_OUT,' ':10,'TRANSMISSION',' ':2,'RECEPTION',' ':4,'WAIT',' ':3);
writeln(ADX_OUT,'COLLISION');

write(AUX_OUT,' ',' ':7,'COLLISIONS':2,'TRANSMITTING',' ':2,'WAITING');
write(AUX_OUT,'ACTIVE',' ':12,'COUNT',' ':4,'RECEIVING':2,' ':5);
write(AUX_OUT,'COUNT',' ':4,'COUNT');  ':8,'COUNT',' ':5;

writeln(AUX_OUT);
LCT:=LCT+5;

for I:=1 to NUM_OF_ADAPTERS do
  for J:=1 to 4 do
    with ADAPTER[I].DEVICE[J] do
      if not OPEN then
      begin
        DEV_ACTIVE_TIME:=TX_TIME+WAIT_TIME+COLL_TIME+RX_TIME;
        write(AUX_OUT,I:4,J:4,TX_TIME:12:4,WAIT_TIME:13:4);
        write(AUX_OUT,TX_CT:13,RX_CT:14,WAIT_CT:8);DEV_ACTIVE_TIME:=13:4);
        writeln(ADX_OUT,COLL_CT:9);
        writeln(AUX_OUT);
        LCT:=LCT+2;
      end;  (* if not OPEN *)

(* Calculate and print percent summaries *)

writeln(AUX_OUT);writeln(AUX_OUT);
writeln(AUX_OUT,' ':45,'DEVICE ACTIVITY SUMMARIES');
writeln(AUX_OUT,' ':53,'(PERCENT)');

write(AUX_OUT,' ':2,'ADP DEV');
write(AUX_OUT,' ':5,'TIME':3,'TIME':8,'TIME':8);
write(AUX_OUT,' ':z,'TIME_IN':6,'TIME_IN':5,'TIME_IN':5);

write(AUX_OUT,' ':14,'ACTIVE',' ':5,'TRANSMITTING',' ':2);
write(AUX_OUT,' ':2,'TRANSMITTING',' ':5,'WAITING':3);
write(AUX_OUT,' ':2,'COLLISIONS':2,' ':7,'(TRUNK)',' ':7);
write(AUX_OUT,' ':13,'(TRUNK)',' ':6,'(TRUNK)',' ':7);
write(AUX_OUT,'(DEVICE)',' ':2,'(TRUNK)',' ':6);
writeln(ADX_OUT,'(DEVICE)');

LCT:=LCT+7;

for I:=1 to NUM_OF_ADAPTERS do
  for J:=1 to 4 do
    with ADAPTER[I].DEVICE[J] do
      if not OPEN then
      begin
        DEV_ACTIVE_TIME:=TX_TIME+WAIT_TIME+COLL_TIME+RX_TIME;
        if DEV_ACTIVE_TIME > 0.0 then
        begin
          PC_TX_TR:=DEV_ACTIVE_TIME/TIME_ACTIVE*100.0;
          PC_TX_TR:=TX_TIME/TIME_ACTIVE*100.0;
          PC_WAIT_TR:=WAIT_TIME/TIME_ACTIVE*100.0;
          PC_COLL_TR:=COLL_TIME/TIME_ACTIVE*100.0;
          if (TX_CT = 0) or (TY_INTRVL = 0.0) then
            PC_TX_DEV:=0
          else
            PC_TX_DEV:=TX_TIME_CT/TX_INTRVL*100.0;
          if (WAIT_CT = 0) or (TX_INTRVL = 0.0) then
            PC_WAIT_DEV:=0
          else
            PC_WAIT_DEV:=WAIT_TIME/WAIT_CT/TX_INTRVL*100.0;
          if (COLL_CT = 0) or (TX_INTRVL = 0.0) then
            PC_COLL_DEV:=0
          else
            PC_COLL_DEV:=COLL_TIME/COLL_CT/TX_INTRVL*100.0;
        end
        else
        begin
          PC_TX_DEV:=0.0;
          PC_WAIT_DEV:=0.0;
          PC_COLL_DEV:=0.0;
          PC_ACT_TR:=0.0;
        end;  (* if DEV_ACT_TIME = 0.0 *)
```

83

```
          write(AUX_OUT,I:4,J:4,PC_ACT_TR:11:2,PC_TX_TR:14:2);
          write(AUX_OUT,PC_TX_DEV:14:2,PC_WAIT_TR:14:2,PC_WAIT_DEV:14:2);
          write(AUX_OUT,PC_COLL_TR:16:2)):
          writeln(AOX_OUT,PC_COLL_DEV:14:2);

          writeln(AUX_OUT);

          LCT:=LCT+2;
        end;  (* not OPEN *)


    NEWPAGE;

A   end;  (* procedure ACTIVITY SUMMARY *)


    (*****************************************)
    (*                                       *)
A   procedure CHARACTERIZE NETWORK;
    (*   prompts for network descriptive info.  *)
    (*********************************************)

    var
    I,J   :integer;

    (*****************************************************)
    (*                                                   *)
B   procedure INITIALIZE PROB_MATRIX;
    (*   Initializes matrix containing the probability   *)
    (*   that any device will request a transmission to  *)
    (*   any other device. Matrix is a 2-D array .       *)
    (*   ROW references refer to sender and columns      *)
    (*   refer to receiver. Each device is assigned a    *)
    (*   unique device number upon program startup       *)
    (*   and these numbers should be used to obtain      *)
    (*   the probabilities.                              *)
    (*****************************************************)

    var
    C,P   : real;
    I,J,K,  : integer;
    ROW    : integer;

B   begin
      C:=0; ROW:=0;

      case INPUT MODE of
      INTERACTIVE: begin
          writeln(OUTPUT);writeln(OUTPUT);
          writeln(OUTPUT):                :12, 'CUMMULATIVE PROBABILITY MATRIX');
          writeln(OUTPUT);
          writeln(OUTPUT,'ENTER PROB OF TX, CUMMULATIVE PROB WILL CALCULATED.');
          writeln(OUTPUT);

          for I:=1 to NUM_OF_ADAPTERS do
            for J:=1 to 4 do
              with ADAPTER[I].DEVICE[J] do
                if not OPEN then
                  write(OUTPUT,I:5,J:1);
          writeln(OUTPUT);

          for I:=1 to NUM_OF_ADAPTERS do
            for J:= 1 to 4 do
              with ADAPTER[I].DEVICE[J] do
                if not OPEN then
                  begin
                    writeln(TERMINAL,I:2,J:1);
                    ROW:=ROW+1;
                    C:=0; K:=1;
                    while K<=B_NUM do
                      begin
                        read(TERMINAL,P);
                        if (C+P) <= 1 then
                          begin
```

```
              PR[ROW,K] := C+P;
              C := C+P;
              K := K+1;
            end
          else
            writeln(OUTPUT,'** ERROR ** REENTER LINE, TOTAL PERCENT CANT BE > 1.0 ');
        end; (* while K <= D_NUM *)
        readln(TERMINAL);
      end; (* not OPEN *)
    end; (* INTERACTIVE case *)

    FILE_INPUT : begin
      for I:= 1 to NUM_OF_ADAPTERS do
        for J:= 1 to 4 do
          with ADAPTER[I].DEVICE[J] do
            if not OPEN then
              begin
                ROW := ROW+1;
                for K:= 1 to D_NUM do
                  read(DESCRIP_FILE,PR[ROW,K]);
                readln(DESCRIP_FILE);
              end; (* for I:= 1 to D_NUM *)
    end; (* FILE case *)

    OTHERWISE : end;

  end; (* procedure to initialize cumulative prob matrix *)

begin (* procedure CHARACTERIZE_NETWORK *)

  writeln(TERMINAL,'Input mode:  INTERACTIVE or FILE');
  readln(TERMINAL,RESP);
  if (RESP[1] = 'I') or (RESP[1] = 'i') then
    INPUT_MODE := INTERACTIVE
  else
    INPUT_MODE := FILE_INPUT;

  (*  Begin description of network by describing adapters   *)

  CASE INPUT_MODE OF

    INTERACTIVE : begin

      writeln('*****************************************');
      writeln('*                                       *');
      writeln('*       DESCRIPTION OF NETWORK          *');
      writeln('*       DEVICE BY DEVICE -- ADAPTER BY ADAPTER');
      writeln;

      for I:= 1 to NUM_OF_ADAPTERS do
        begin
          with ADAPTER[I] do
            begin
              writeln;
              writeln('Adapter #',I:2,':');
              J:= 1;
              while J<I do
                begin
                  writeln(TERMINAL,' ':2,'Propagation distance in sec to adapter ',J:2,' is ');
                  readln(TERMINAL,PROP_DIST_TO[J]);
                  J:= J+1;
                end; (* while J<K *)
              if J=1 then J:=J+1;
              while (J>1) and (J<=MAX_NUM_ADAPTERS) DO
                begin
                  writeln(TERMINAL,' ':2,'Propagation distance in sec to adapter ',J:2,' is ');
                  readln(TERMINAL,PROP_DIST_TO[J]);
                  J:= J+1;
                end; (* while J>I AND <= MAX NUM OF ADAPTERS *)
              writeln;
              writeln(TERMINAL,' ':2,'Adapter #',I:2,' fixed delay in sec is ');
              readln(TERMINAL,PRIORITY_DELAY);
```

85

```
writeln(TERMINAL,'  ':13,' end delay in sec is ');
readln(TERMINAL,END_DELAY);

(*  Begin individual device descriptions  *)

for J:= 1 to 4 do
  begin
    with ADAPTER[I].DEVICE[J] do
    begin
      OPEN:= true;
      writeln;
      writeln('  ':2,'Adapter ',I:2,' Device ',J:2,' description:');
      writeln(TERMINAL,'  ':4,'Device status (OPEN or CLOSED):?');
      readln(TERMINAL,RESP);
      if (RESP[1]='c') or (RESP[1]='C') then
         OPEN:=false;
      if not(OPEN) then
      begin
        D_NUM:=D_NUM+1;
        DEV_NUM:=D_NUM*100 + I*10 +J;
        writeln(TERMINAL,'  ':4,'Buffer size (Bytes) ');

        (* Change bytes to bits for storage *)
        readln(TERMINAL,BUFFER_SIZE);
        BUFFER_SIZE:=BUFFER_SIZE*8;

        writeln(TERMINAL,'  ':4,'I/O bus transfer rate',' (Bps)');
        readln(TERMINAL,TFER_RATE);
        TFER_RATE:=TFER_RATE*8;

        LOAD_TIME:=1.0/TFER_RATE;

        writeln(TERMINAL,'  ':4,'Number of offnet sources for device:');
        readln(TERMINAL,NUM_OF_SOURCES);

        for K:=1 to NUM_OF_SOURCES do
        begin
          writeln(TERMINAL,'  ':6,'Source #',K:2,' transmission rate',' (bps)');
          readln(TERMINAL,SOURCE[K].TX_RATE);
          SOURCE[K].TX_RATE:=SOURCE[K].TX_RATE*8;
          TX_INTRVL:= for k:=1 to num of sources *)
          TX_INTRVL:=TX_INTRVL;
          NEXT_TX:=TX_INTRVL;
        end;  (* for K *)
        If not(OPEN)
      end;  (* if not(OPEN) *)
    end;  (* with ADAPTER[I].DEVICE[J] *)
  end;  (* for J:=1 TO 4 *)
end;  (* with ADAPTER[I] *)
end;  (* for I:=1 to num of adapters *)
INITIALIZE PROB MATRIX;
end;  (* INTERACTIVE case *)

FILE_INPUT : begin
  reset(DESCRIP_FILE);
  for I:= 1 to NUM_OF_ADAPTERS DO
  begin
    with ADAPTER[I] DO
    begin
      J:=1;
      while J<I do
      begin
        readln(DESCRIP_FILE,PROP_DIST_TO[J]);
        J:=J+1;
      end;  (* while J<K *)

      if J=I then J:=J+1;

      while (J>I) and (J<=MAX_NUM_ADAPTERS) DO
      begin
        readln(DESCRIP_FILE,PROP_DIST_TO[J]);
        J:=J+1;
      end;  (* while J>I AND <= MAX_NUM OF ADAPTERS *)

      readln(DESCRIP_FILE,PRIORITY_DELAY);
      readln(DESCRIP_FILE,END_DELAY);

(*  Begin individual device descriptions  *)

      for J:= 1 to 4 do
        begin
```

```
with ADAPTER[I].DEVICE[J] do
  begin
    readln(DESCRIP_FILE,RESP);
    if (RESP[8]='F') or (RESP[8]='f') then
      OPEN:=false
    ELSE
      OPEN:=TRUE;
    if not(OPEN) then
      begin
        readln(DESCRIP_FILE,DEV_NUM);
        D_NUM:=DEV_NUM DIV 100;
        readln(DESCRIP_FILE,BUFFER_SIZE);
        readln(DESCRIP_FILE,TFER_RATE);
        LOAD_TIME:=1.0/TFER_RATE;
        readln(DESCRIP_FILE,NUM_OF_SOURCES);
        for K:=1 to NUM_OF_SOURCES do
          begin
            readln(DESCRIP_FILE,SOURCE[K].TK_RATE);
          end; (* for K:=1 to num of sources *)
        TK_INTRVL := TK_INTERVAL(ADAPTER[I].DEVICE[J]);
        NEXT_TK := TK_INTRVL;
      end; (* if not(OPEN) *)
    end; (* with ADAPTER[I].DEVICE[J] *)
  end; (* for J:=1 to 4 *)
end; (* for I:=1 to num of adapters *)
INITIALIZE_PROB_MATRIX;
end; (* FILE_INPUT case *)

otherwise : end; (* case *)

end; (* procedure CHARACTERIZE_NETWORK *)

(*****************************************************)
(*                                                   *)
procedure PRINT_NET_DESCRIPTION;
(*  prints the description of the entire             *)
(*  network.                                         *)
(*****************************************************)

var
  I,L,J,K,
  LL,ROW : integer;

begin  (* procedure PRINT_DESCRIPTION *)
  ROW:=0;

  rewrite(AUX_OUT);
  for I:=1 to NUM_OF_ADAPTERS do
    begin
      NEWPAGE;
      writeln(AUX_OUT,' ':10,'*****************************************');
      writeln(AUX_OUT,' ':10,'*                                       *');
      writeln(AUX_OUT,' ':10,'*           NETWORK DESCRIPTION          *');
      writeln(AUX_OUT,' ':10,'*            Adapter #',I:1:3,'           *');
      writeln(AUX_OUT,' ':10,'*                                       *');
      writeln(AUX_OUT,' ':10,'*****************************************');
      LCT:=LCT+9;
      with ADAPTER[I] DO
        begin
          writeln(AUX_OUT);writeln(AUX_OUT);
          writeln(AUX_OUT,'Adapter #',I:2,' : ');
          J:=1;LCT:=LCT+3;
          while J<I do
            begin
              write(AUX_OUT,' ':6,'Propagation distance to adapter ',J:2,': ');
              writeln(AUX_OUT,PROP_DIST_TO[J]:9:7,' sec');
              LCT:=LCT+J;
```

```
         J:=J+1;
      end;  (* while J<K *)

      if J=1 then J:=J+1;

      while (J>1) and (J<=MAX_NUM_ADAPTERS) DO
      begin
         write(AUX_OUT,' ':6,'Propagation distance to adapter ',J:2,': ');
         writeln(ADX_OUT,PROP_DIST_TO[J]:9:7,' sec');
         LCT:=LCT+1;
         J:=J+1;
      end;  (* while J>1 AND <= MAX NUM OF ADAPTERS *)

      writeln(AUX_OUT);
      LCT:=LCT+1;
      writeln(AUX_OUT,' ':6,'Priority delay: ');
      writeln(ADX_OUT,PRIORITY_DELAY:9:7,' sec');
      LCT:=LCT+1;
      writeln(AUX_OUT,' ':6,'End delay: ');
      writeln(ADX_OUT,END_DELAY:9:7,' sec');
      LCT:=LCT+2;

      (* Begin individual device descriptions *)

      for J:= 1 to 4 do
      begin
         with ADAPTER[I].DEVICE[J] do
         begin
            writeln(AUX_OUT);
            LCT:=LCT+1;
            writeln(AUX_OUT,' ':6,'Device ',J:2);
            write(AUX_OUT,' ':2,'Status: ');
            if OPEN then begin writeln(AUX_OUT,'OPEN');
               LCT:=LCT+1; end
            else writeln(AUX_OUT,'CLOSED');
            if not(OPEN) then
            begin
               writeln(AUX_OUT,' ':2,'Device number ',DEV_NUM:2);
               LCT:=LCT+1;
               write(AUX_OUT,' ':2,'Buffer size: ');
               writeln(ADX_OUT,BUFFER_SIZE DIV 8:8,' Bytes');
               LCT:=LCT+1;
               write(AUX_OUT,' ':2,'I/O transfer rate: ');
               writeln(ADX_OUT,TFER_RATE/8:12:2,' Bps');
               LCT:=LCT+1;
               writeln(AUX_OUT,' ':2,'Load time: ',LOAD_TIME:12:7,' sec');
               LCT:=LCT+1;
               writeln(AUX_OUT,' ':2,'Number of offnet sources:');
               writeln(ADX_OUT,NUM_OF_SOURCES:3);
               LCT:=LCT+1;
               for K:=1 to NUM_OF_SOURCES do
               begin
                  write(AUX_OUT,' ':4,'Source #',K:2,' transmission rate: ');
                  writeln(ADX_OUT,SOURCE[K].TX_RATE/8:9:2,' Bps');
                  LCT:=LCT+1;
               end;  (* for K:=1 to num of sources *)
               writeln(AUX_OUT,' ':2,'Trunk transmission interval: ',TX_INTRVL:7:4,' sec');
               LCT:=LCT+1;
            end;  (* if not(OPEN) *)
         end;  (* with ADAPTER[I].DEVICE[J] *)
      end;  (* for J:=1 to 4 *)
   end;  (* for I=1 with ADAPTER[I] *)

   NEWPAGE;
   writeln(AUX_OUT,' ':6,'CUMMULATIVE PROBABILITY OF TRANSMISSION MATRIX');
   writeln(AUX_OUT);
   writeln(AUX_OUT);
   LCT:=LCT+3;

   write(AUX_OUT,' ':5);
   for I:= 1 to NUM_OF_ADAPTERS do
      for J:= 1 to 4 do
         with ADAPTER[I].DEVICE[J] do
            if not OPEN then
               write(AUX_OUT,I:6,J:1);
```

```
      writeln(AUX_OUT);
      LCT:=LCT+1;

      for I:=1 to NUM_OF_ADAPTERS do
        for J:=1 to Z do
          with ADAPTER[I].DEVICE[J] do
            if not OPEN then
              begin
                write(AUX_OUT,I:4,J:1);
                ROW:=ROW+T;
                for K:=1 to D_NUM do
                  begin
                    write(AUX_OUT,PR[ROW,K]:7:2);
                  end; (* for K *)
                writeln(AUX_OUT);
                LCT:=LCT+1;
              end; (* not OPEN *)
      end;  (* procedure PRINT DESCRIPTION *)

(*********************************************)
(*                                           *)
(*     PROCEDURE CREATE_DESCRIP_FILE;        *)
(*     WRITES TO THE AUXILLIARY INPUT FILE   *)
(*                                           *)
(*********************************************)

begin  (* procedure CREATE *)

  rewrite(DESCRIP_FILE);
  for I:=1 to NUM_OF_ADAPTERS do
    begin
      with ADAPTER[I] DO
        begin
          J:=1;
          while J<I do
            begin
              writeln(DESCRIP_FILE,PROP_DIST_TO[J]);
              J:=J+1;
            end; (* while J<K *)

          if J=I then J:=J+1;

          while (J>I) and (J<=MAX_NUM_ADAPTERS) DO
            begin
              writeln(DESCRIP_FILE,PROP_DIST_TO[J]);
              J:=J+1;
            end; (* while J>I AND <= MAX NUM OF ADAPTERS *)

          writeln(DESCRIP_FILE,PRIORITY_DELAY);
          writeln(DESCRIP_FILE,END_DELAY);

  (* Begin individual device descriptions *)

          for J:=1 to 4 do
            begin
              with ADAPTER[I].DEVICE[J] do
                begin
                  writeln(DESCRIP_FILE,OPEN);
                  if not(OPEN) then
                    begin
                      writeln(DESCRIP_FILE,DEV_NUM);
                      writeln(DESCRIP_FILE,BUFFER_SIZE);

                      writeln(DESCRIP_FILE,TFER_RATE);

                      writeln(DESCRIP_FILE,NUM_OF_SOURCES);

                      for K:=1 to NUM_OF_SOURCES do
                        begin
                          writeln(DESCRIP_FILE,SOURCE[K].TX_RATE);
                      end; (* for k:=1 *) (* to num of sources *)
                    end; (* if not(OPEN) *)
                end; (* with ADAPTER().DEVICE() *)
            end; (* for J:=1 TO 4 *)
        end; (* with ADAPTER() *)
    end; (* for I:=1 to num of adapters *)
```

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```pascal
                (* write the probability matrix *)
                for I:=1 to D_NUM do
                  begin
                    for J:= 1 to D_NUM do
                      write(DESCRIP_FILE,PR[I,J]);
                      writeln(DESCRIP_FILE);
                  end;
              end;  (* procedure CREATE *)

          {************************************}
          {*                                  *}
          {*      M A I N   P R O G R A M     *}
          {*                                  *}
          {************************************}

          begin  (* main program *)

          (* New run initializations *)

          for COND1 := NORMAL to OTHER do
            CONDITION[COND1] := COND1;

          PRINT_ALL := true;

          U:= 31622 ; (* U is seed for RNG *)
          WAIT_TALL :=0;
          COLLISION_TALLY:=0;
          TOTAL_ATTEMPTS:=0;
          TOTAL_ATTEMPTS:=0;
          LCT:=0;
          PCT:=0;
          TIME_ACTIVE:=0.0;
          BITS_TX:=0;

          writeln;
          writeln(TERMINAL,"Maximum run time in secs?");
          readln(TERMINAL,MAX_TIME);
          writeln;

          writeln(TERMINAL,"Maximum successful transmissions?");
          readln(TERMINAL,MAX_TX);
          writeln;

          writeln;
          writeln(TERMINAL,"Seed for random number generator?");
          readln(TERMINAL,U);IU:=U;
          writeln;

          writeln(TERMINAL,"PRINT_ALL condition on?");
          readln(TERMINAL,RESP);
          if (RESP[1] ="y") or (RESP[1] ="Y") then
            PRINT_ALL:= true
          else
            PRINT_ALL:= false;

          writeln;

          (* Network cold start conditions *)

          CHARACTERIZE_NETWORK;

          page(OUTPUT);
          CREATE_DESCRIP_FILE;

          PRINT_NET_DESCRIPTION ;

          FIND_NEXT(TMITTR);

          CURRENT_TIME:= TMITTR.NEXT_TX;

          (* Network steady state operation *)

          repeat  (* until time exceeds max time *)
```

90

```
PICK_A(RCVR,TMITTR);

(* Calculate a collision probability *)

if not A_COLLISION then
  begin
    TX_TALLY := TX_TALLY+1;
    UPDATE_CLOCKS(CONDITION[NORMAL]);
    if PRINT_ALL then
      PRINT_TX_STATS(TMITTR,RCVR);

    FIND_NEXT(TMITTR);

    CURRENT_TIME:=TMITTR.NEXT_TX;
  end
  else
    begin
      COLLISION_TALLY := COLLISION_TALLY +1;
      UPDATE_CLOCKS(CONDITION[COLLISION]);

      if PRINT_ALL then
        PRINT_COLLISION_STATS(TMITTR,RCVR);

      FIND_NEXT(TMITTR);

      CURRENT_TIME:= TMITTR.NEXT_TX;

    end; (* if *)

until (CURRENT_TIME >= MAX_TIME) or (TX_TALLY >= MAX_TX);

TOTAL_ATTEMPTS:=TX_TALLY+COLLISION_TALLY;

PRINT_NETWORK_STATS;

ACTIVITY_SUMMARY;

writeln(" END OF RUN");

end. (* main program *)
```

Compilation complete - no errors found.

```
@MAP,I  ,HOSC.XQT
MAP 30R1 S74111 07/01/83 16:39:18
START=02D075. PROG SIZE(I/D)=7747/4772
SYS8+RLIB8.LEVEL
END MAP.  ERRORS:  0  TIME: 9.310  STORAGE: 12160/3/025777/073777
```

@XQT HOSC.XQT

Maximum run time in secs?

Maximum successful transmissions?

Seed for random number generator?

PRINT_ALL condition on?

Input mode: INTERACTIVE or FILE

C-2

```
*** END OF RUN ***
Current Time: 36.4361 secs

Successful transmissions:  500
Collisions            :     29
Waits                 :     8?
Total attempts        :    529

Total time active     :  1.7105 secs
% Total time active   :  4.62%

Total Bytes transmitted :   987360

Seed for RNG          :   312577

END OF RUN

@BRK,Y
```

*** END OF RUN NETWORK STATISTICS ***

Current time: 35.4361 secs

Successful transmissions: 520
Collisions   :   29
Waits   :   86
Total attempts   :   529

Total time active   : 1.7935225 secs
% Total time active : 4.6938 secs

Total Bytes transmitted : 987360

Seed for RNG   : 312577

92

DEVICE ACTIVITY SUMMARIES (SECONDS)

ADP #	DEV #	TIME TRANSMITTING	TIME WAITING	TIME IN COLLISIONS	TIME RECEIVING	TIME ACTIVE	TRANSMISSION COUNT	RECEPTION COUNT	WAIT COUNT	COLLISION COUNT
1	1	0.9198	0.3897	0.0273	0	1.3357	252	0	39	20
2	1	0.2711	0.4398	0.0045	0	0.7153	35	0	37	3
2	2	0.4324	0.0037	0.0011	0.0012	0.4393	35	2	1	1
3	1	0.0410	0.0110	0.0043	0.6938	0.7500	71	249	3	3
3	2	0.0410	0.0073	0	0.3059	0.3552	71	143	2	0
3	3	0.0052	0.0037	0.0035	0	0.0123	36	0	1	2
4	1	0	0	0	0	0	0	0	0	0
4	2	0	0	0	0.4376	0.4376	0	71	0	0
4	3	0	0	0	0.2711	0.2711	0	35	0	0

DEVICE ACTIVITY SUMMARIES (PERCENT)

ADP	DEV	% TIME ACTIVE (TRUNK)	% TIME TRANSMITTING (T-TRUNK)	% TIME TRANSMITTING (DEVICE)	% TIME TRANSMITTING	% TIME WAITING (DEVICE)	% TIME IN COLLISIONS (TRUNK)	% TIME IN COLLISIONS (DEVICE)
1	1	78.15	5.77	2.61	22.78	7.15	1.59	0.98
2	1	41.82	1.85	0.77	25.71	1.19	0.26	0.15
2	2	25.52	25.28	1.24	0.21	0.37	0.06	0.11
3	1	43.85	2.40	0.11	0.54	0.71	0.25	0.28
3	2	20.77	2.40	0.11	0.43	0.71	0	0
3	3	0.72	0.30	0.01	0.21	0.37	0.20	0.17
4	1	0	0	0	0.21	0	0.20	0
4	2	25.58	0	0	0	0	0	0
4	3	15.85	0	0	0	0	0	0

NETWORK DESCRIPTION
Adapter # 1

Adapter # 1:
Propagation distance to adapter 2:   0 sec
Propagation distance to adapter 3:   0 sec
Propagation distance to adapter 4:   0 sec

Priority delay: 0 sec
End delay: 0.0300010 sec

Device 1   status: CLOSED   Device number 111   2096 Bytes
                                Buffer size:
                                I/O bus transfer rate: 500000.00 Bps
                                Load time: 0.0000002 sec
                                Number of offnet sources: 1
                                   Source #1 transmission rate: 15000.00 Bps
                                   Trunk transmission interval: 0.1337 sec

Device 2   status: OPEN

Device 3   status: OPEN

Device 4   status: OPEN

94

```
                    NETWORK DESCRIPTION
                       Adapter # 2


Adapter # 2:
Propagation distance to adapter 1:        0 sec
Propagation distance to adapter 3:        0 sec
Propagation distance to adapter 4:        0 sec

Priority delay:    0 sec
End delay:      0.0000020 sec

Device 1    status: CLOSED    Device number 221
                             Buffer size:     4000 Bytes
                             I/O bus transfer rate: 5000000.00 Bps
                             Load time:    0.000002 sec
                             Number of offnet sources: 1
                                 Source #1 transmission rate:   4000.00 Bps
                                 Trunk transmission interval:  1.0000 sec

Device 2    status: CLOSED    Device number 322
                             Buffer size:     6400 Bytes
                             I/O bus transfer rate: 5000000.00 Bps
                             Load time:    0.000002 sec
                             Number of offnet sources: 1
                                 Source #1 transmission rate:   6400.00 Bps
                                 Trunk transmission interval:  1.0000 sec

Device 3    status: OPEN
Device 4    status: OPEN
```

```
**************************************
**************************************
      ********************************
      ********************************
      ********************************

          NETWORK DESCRIPTION
            Adapter # 3

Adapter # 3:
 Propagation distance to adapter 1:        0 sec
 Propagation distance to adapter 2:        0 sec
 Propagation distance to adapter 4:        0 sec

 Priority delay:     0.000000 sec
 End delay:          0.000000 sec

Device 1    status: CLOSED    Device number 431    512 Bytes
                              Buffer size:       512 Bytes
                              I/O bus transfer rate: 500000.00 Bps
                              Load time:        0.000002 sec
                              Number of offnet sources: 1
                                Source #1 transmission rate:   1000.00 Bps
                              Trunk transmission interval:   0.5120 sec

Device 2    status: CLOSED    Device number 532    512 Bytes
                              Buffer size:       512 Bytes
                              I/O bus transfer rate: 500000.00 Bps
                              Load time:        0.000002 sec
                              Number of offnet sources: 1
                                Source #1 transmission rate:   1000.00 Bps
                              Trunk transmission interval:   0.5120 sec

Device 3    status: CLOSED    Device number 633    624 Bytes
                              Buffer size:       624 Bytes
                              I/O bus transfer rate: 330000.00 Bps
                              Load time:        0.000000 sec
                              Number of offnet sources: 1
                                Source #1 transmission rate:    625.00 Bps
                              Trunk transmission interval:   0.9984 sec

Device 4    status: OPEN
```

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```
NETWORK DESCRIPTION
    Adapter # 4
```

Adapter # 4:
Propagation distance to adapter   1:   0 sec
Propagation distance to adapter   2:   0 sec
Propagation distance to adapter   3:   0 sec

Priority delay: 0.000000 sec
End delay: 0.000000 sec

Device 1   status: CLOSED   Device number 741
                             Buffer size: 2000 Bytes
                             I/O bus transfer rate: 300000.00 Bps
                             Load time: 0.000000 sec
                             Number of offnet sources: 0
                             Trunk transmission interval: 10000000.000699 sec

Device 2   status: CLOSED   Device number 842
                             Buffer size: 2000 Bytes
                             I/O bus transfer rate: 1200000.00 Bps
                             Load time: 0.000001 sec
                             Number of offnet sources: 0
                             Trunk transmission interval: 10000000.000699 sec

Device 3   status: CLOSED   Device number 943
                             Buffer size: 2000 Bytes
                             I/O bus transfer rate: 1200000.00 Bps
                             Load time: 0.000001 sec
                             Number of offnet sources: 0
                             Trunk transmission interval: 10000000.000699 sec

Device 4   status: OPEN
```

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CUMULATIVE PROBABILITY OF TRANSMISSION MATRIX